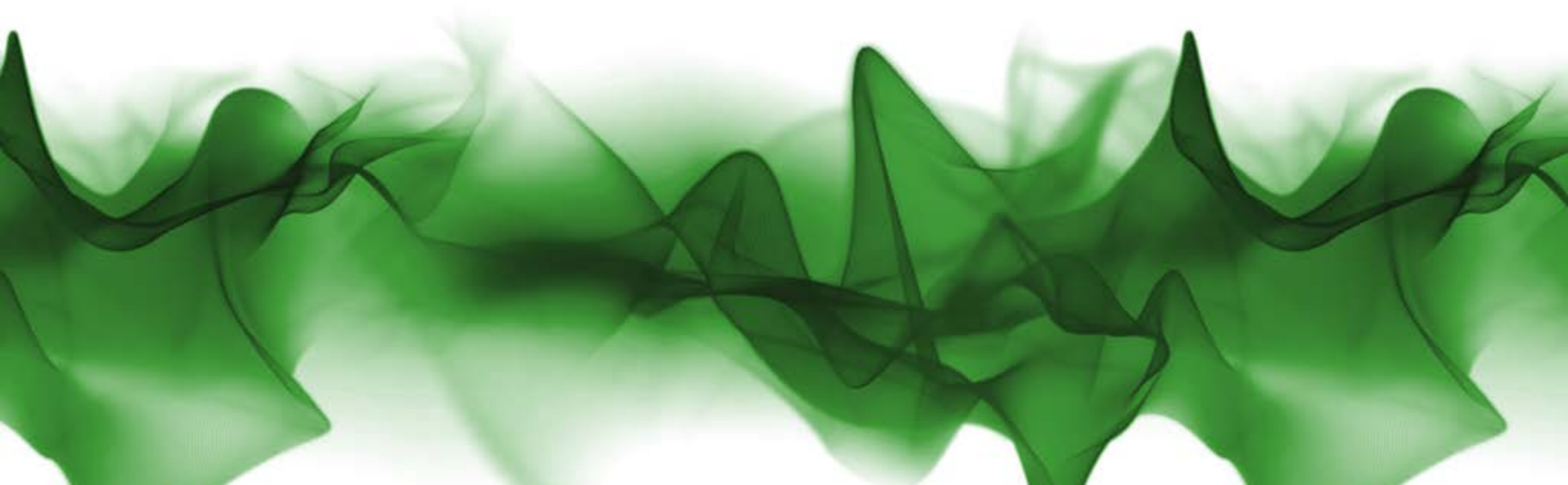


International Iranian Conference on Quantum Information, 7-10 Sept 2014, Esfahan, Iran



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University of Turku
Finland

10 things you always wanted to know about non-Markovian open quantum systems





What do you **exactly** mean
with **non-Markovian** open
quantum systems?

$$\rho(t) = \Lambda_t \rho(0)$$

dynamical map



$$\dot{\rho}(t) = L_t \rho(t)$$

master equation

$$\Lambda_t = \mathbb{T} \exp \left(\int_0^t L_\tau d\tau \right)$$

completely positive (CP) and
trace preserving

$$\rho(t) = \Lambda_t \rho(0)$$

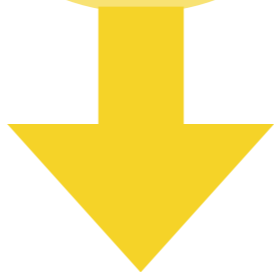
Φ is completely positive (CP) if

$\mathbb{1}_k \otimes \Phi$ is positive for all $k = 1, 2, \dots$

$$\Lambda_t = V_{t,s} \Lambda_s$$

propagator

$$\text{CP } \Lambda_t = V_{t,s} \Lambda_s \text{ CP}$$



CP ?

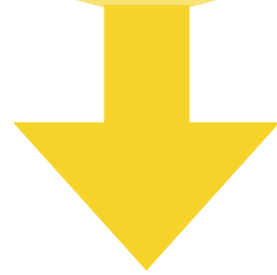


YES

NO

MAYBE

$$\Lambda_t = V_{t,s} \Lambda_s$$



CP

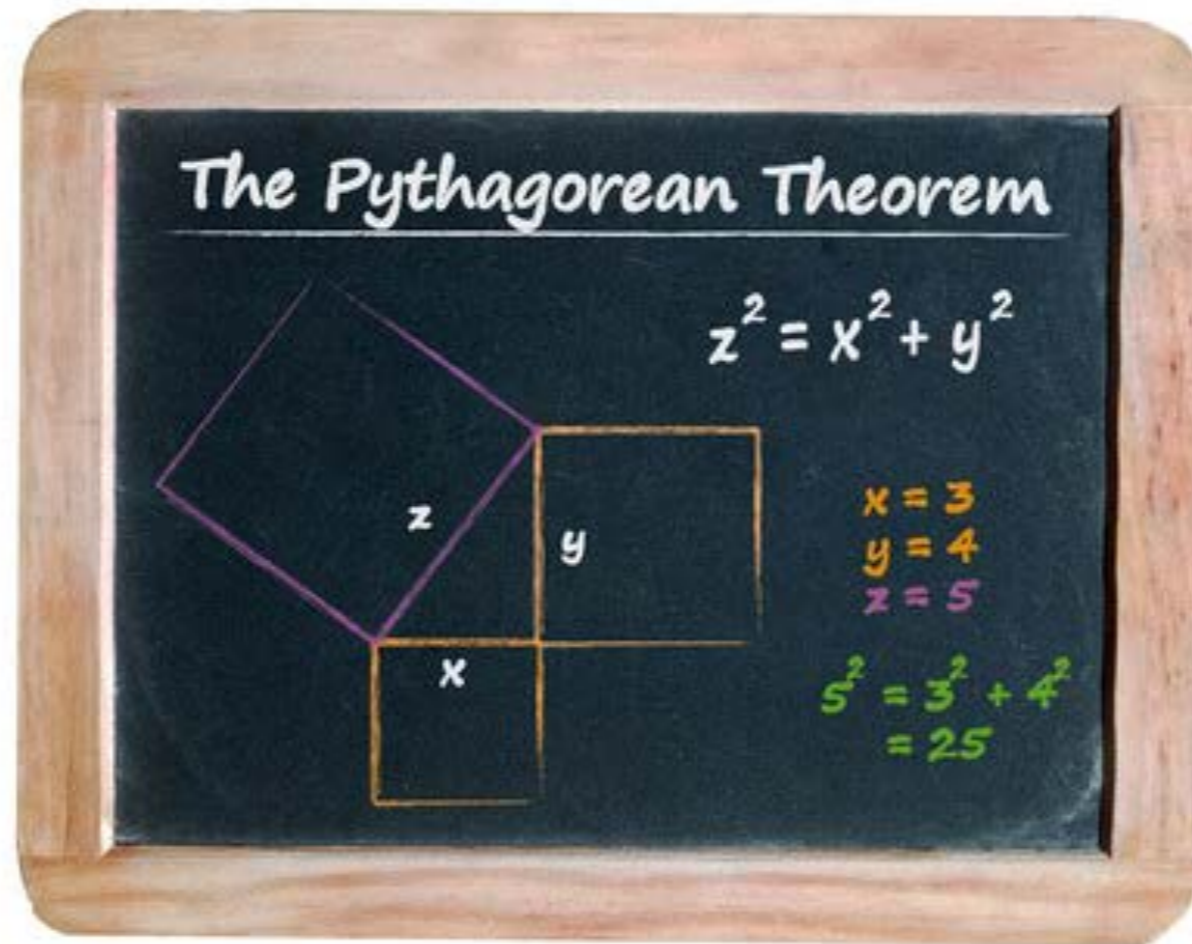
The dynamical map is (CP) divisible

$$\Lambda_t = V_{t,s} \Lambda_s$$

not CP

The dynamical map is (CP) non-divisible

The “Pythagorean theorem” of Open Quantum Systems theory



Λ_t is divisible if and only if L_t can be written in the Lindblad form

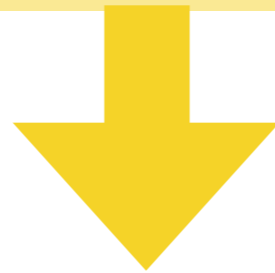
$$L_t(\rho) = -i[H(t), \rho] + \sum_k \left(A_k(t)\rho A_k^\dagger(t) - \frac{1}{2}\{A_k^\dagger(t)A_k(t), \rho\} \right)$$

$$\dot{\rho}(t) = L_t\rho(t)$$

V. Gorini, A. Kossakowski, and E. C. G. Sudarshan, J. Math. Phys. 17, 821 (1976)

G. Lindblad, Comm. Math. Phys. 48, 119 (1976)

$$L_t(\rho) = -i[H(t), \rho] + \sum_k \left(A_k(t) \rho A_k^\dagger(t) - \frac{1}{2} \{A_k^\dagger(t) A_k(t), \rho\} \right)$$



$$L_t(\rho) = -i[H, \rho] + \sum_k \gamma_k(t) \left(A_k \rho A_k^\dagger - \frac{1}{2} \{A_k^\dagger A_k, \rho\} \right)$$

time-dependent decay rates

$$L_t(\rho) = -i[H, \rho] + \sum_k \gamma_k(t) \left(A_k \rho A_k^\dagger - \frac{1}{2} \{A_k^\dagger A_k, \rho\} \right)$$

$$\gamma_k(t) \geq 0 \iff \Lambda_t \text{ divisible}$$

MARKOVIAN

$$L_t(\rho) = -i[H, \rho] + \sum_k \gamma_k(t) \left(A_k \rho A_k^\dagger - \frac{1}{2} \{A_k^\dagger A_k, \rho\} \right)$$

$\gamma_k(t) < 0 \iff \Lambda_t$ nondivisible

NON-MARKOVIAN



Are the quantum and classical definitions of Markovian dynamics different?

Yes!



Classical definition of Markovian stochastic process

$$\{x_i\}_{i \in \mathbb{N}}$$

$$p_{1|n}(x_n, t_n | x_{n-1}, t_{n-1}; \dots; x_0, t_0) = p_{1|1}(x_n, t_n | x_{n-1}, t_{n-1})$$

$$t_n \geq t_{n-1} \geq \dots \geq t_1 \geq t_0$$

***n*-time probabilities**

Classical definition of Markovian stochastic process

$$\{x_i\}_{i \in \mathbb{N}}$$

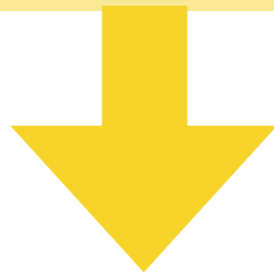
$$p_{1|n}(x_n, t_n | x_{n-1}, t_{n-1}; \dots; x_0, t_0) = p_{1|1}(x_n, t_n | x_{n-1}, t_{n-1})$$

$$t_n \geq t_{n-1} \geq \dots \geq t_1 \geq t_0$$

quantum conditional probabilities

MARKOVIAN

$$p_{1|n}(x_n, t_n | x_{n-1}, t_{n-1}; \dots; x_0, t_0) = p_{1|1}(x_n, t_n | x_{n-1}, t_{n-1})$$



Chapman-Kolmogorov equation

$$p_{1|1}(x, t | y, s) = \sum_z p_{1|1}(x, t | z, \tau) p_{1|1}(z, \tau | y, s)$$

$$\mathbf{p}(t) = \Lambda(t, s) \mathbf{p}(s)$$

stochastic matrix



Is there a **unique** definition
of non-Markovian open
quantum systems

Non-Markovianity *definitions*

and corresponding measures

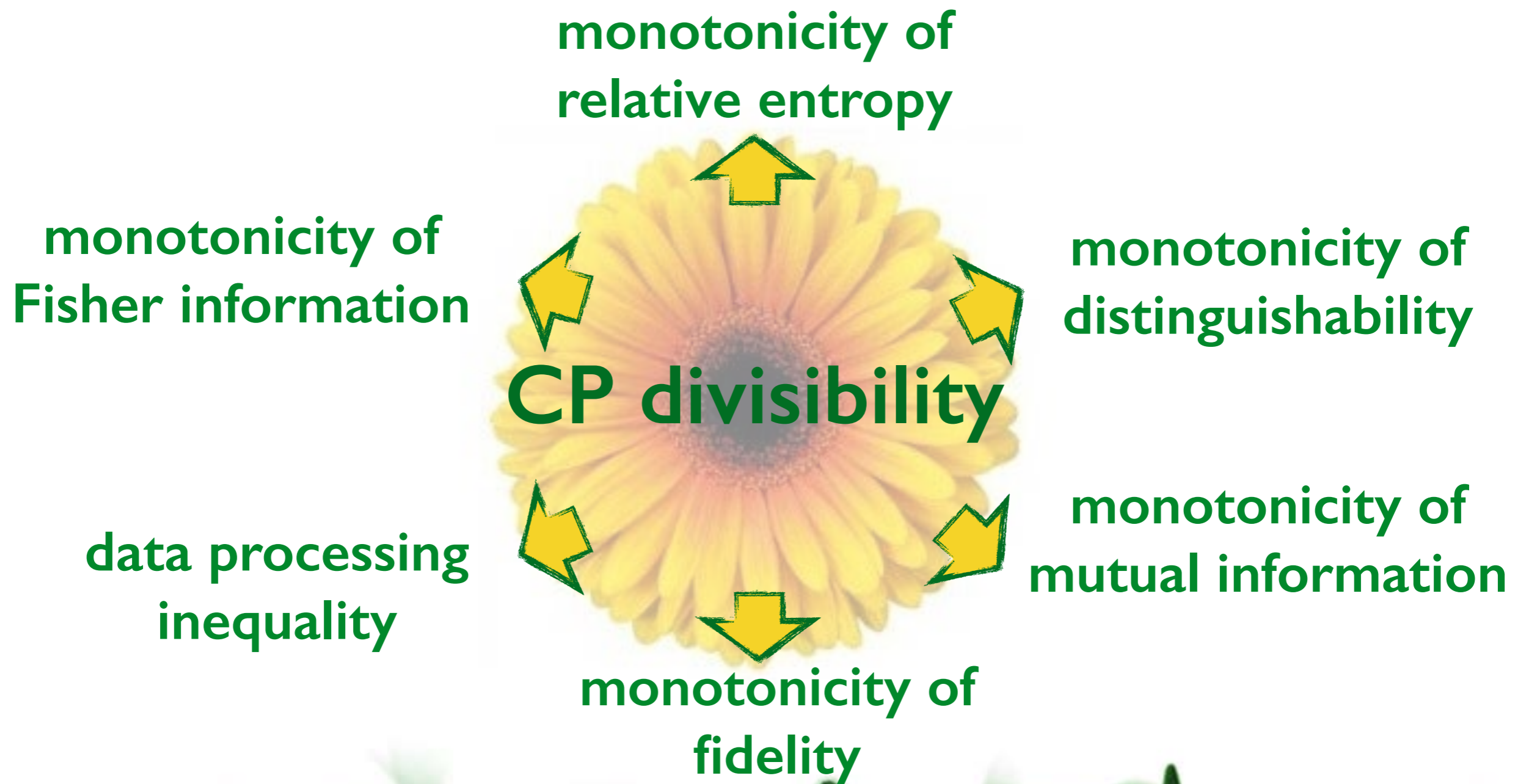
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2. A. Rivas, S.F. Huelga, and M.B. Plenio, Phys. Rev. Lett. 105, 050403 (2010)
3. Xiao-Ming Lu, Xiaoguang Wang, and C. P. Sun Phys. Rev. A 82 042103 (2010)
4. S. C. Hou, X. X. Yi, S. X. Yu, and C. H. Oh, Phys. Rev. A 83 062115 (2011)
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6. L. Mazzola, C. A. Rodríguez-Rosario, K. Modi, and M. Paternostro Phys. Rev. A 86, 010102(R) (2012)
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10. B. Bylicka, D. Chruściński and S. Maniscalco, Scientific Reports 4, 5720 (2014).
11. S. Haseli, S. Salimi, arXiv:1406.0180
12. N. Lo Gullo, I. Sinayskiy, Th. Busch, F. Petruccione, arXiv:1401.1126.
13. F. Buscemi and N. Datta, 1408.7062v1.

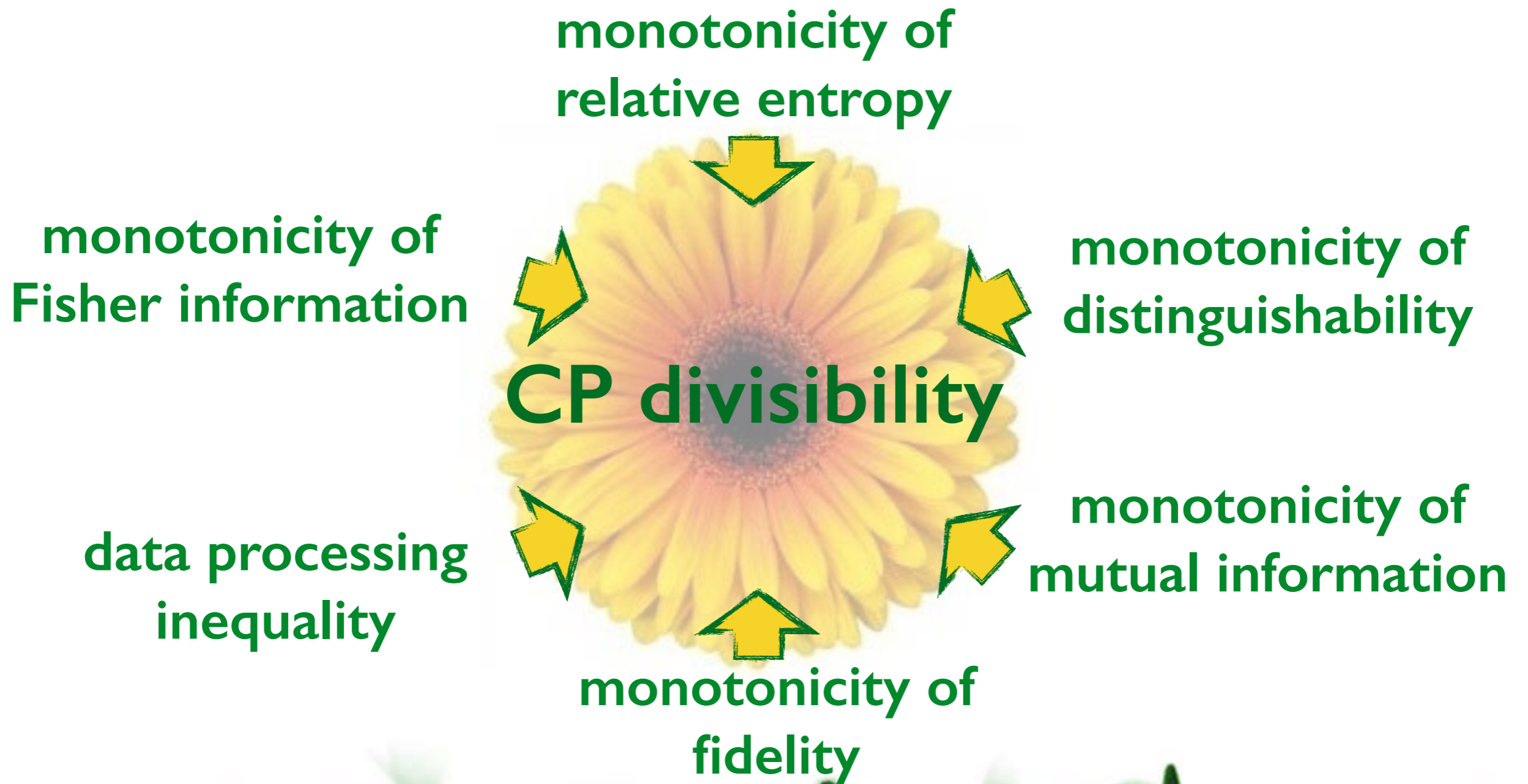


No... Really?

A common feature to all the measures



But the inverse is **NOT** true !



BLP Measure and information flow

$$D(\rho_t^1, \rho_t^2) = \frac{1}{2} \text{Tr} \|\rho_t^1 - \rho_t^2\|, \quad \longrightarrow \quad \text{distinguishability}$$

initial pair of states



states at time t

information loss

BLP Measure and information flow

$$D(\rho_t^1, \rho_t^2) = \frac{1}{2} \text{Tr} \|\rho_t^1 - \rho_t^2\|,$$

$$D(\Lambda_t \rho^1, \Lambda_t \rho^2) \leq D(\rho^1, \rho^2)$$

information flow $\sigma(t, \rho^1, \rho^2) = \frac{d}{dt} D(\Lambda_t \rho^1, \Lambda_t \rho^2)$

$$\sigma(t, \rho^1, \rho^2) \leq 0$$

information loss

$$\sigma(t, \rho^1, \rho^2) > 0$$

information backflow

BLP Measure and information flow

information flow $\sigma(t, \rho^1, \rho^2) = \frac{d}{dt} D(\Lambda_t \rho^1, \Lambda_t \rho^2)$

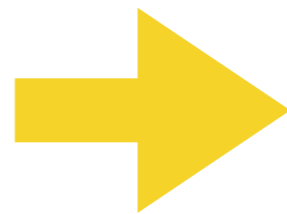
$$\mathcal{N}_{BLP}(\Lambda_t) = \max_{\rho^1, \rho^2} \int_{\sigma > 0} dt \sigma(t, \rho^1, \rho^2)$$

information flow

$$\sigma(t, \rho^1, \rho^2) = \frac{d}{dt} D(\Lambda_t \rho^1, \Lambda_t \rho^2)$$

CP-divisibility

Markovianity



$$\sigma(t, \rho^1, \rho^2) \leq 0$$

information loss

$$\sigma(t, \rho^1, \rho^2) > 0$$

information backflow



non-divisibility

non-Markovianity



Is there a **hierarchy** among the different non-Markovianity measures?

YES

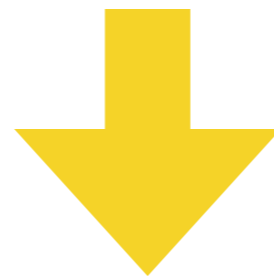
NO

MAYBE

**Analogy between
Entanglement theory**

&

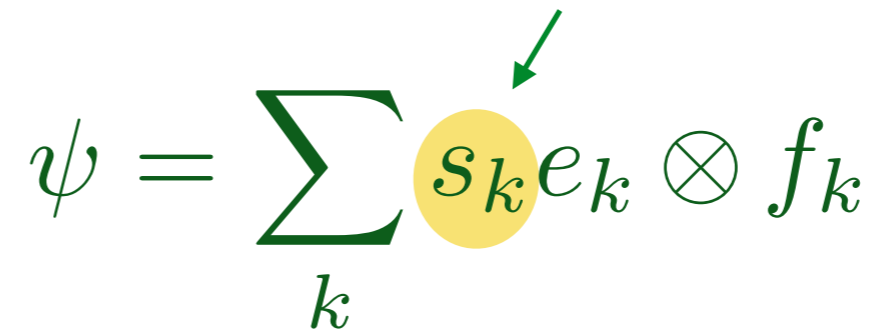
Open system dynamics



Degree of non-Markovianity

Schmidt rank $SR(\psi)$ number of non vanishing Schmidt coefficients

$$\psi \in \mathcal{H} \otimes \mathcal{H}$$

$$\psi = \sum_k s_k e_k \otimes f_k$$


Schmidt number

$$SN(\rho) = \min_{p_k, \psi_k} \{ \max_k SR(\psi_k) \}$$


$$\rho = \sum_k p_k |\psi_k\rangle \langle \psi_k|$$

$$\text{SN}(\rho) = \min_{p_k, \psi_k} \left\{ \max_k \text{SR}(\psi_k) \right\}$$

set of states $S_k = \{ \rho \mid \text{SN}(\rho) \leq k \}$

$$S_1 \subset S_2 \subset \dots \subset S_n$$

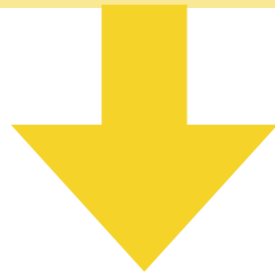
separable states

all states

duality between k -positive maps and bipartite states in S_k

Φ k -positive

$\mathbb{1}_k \otimes \Phi$ positive



$\forall \rho \in S_k$

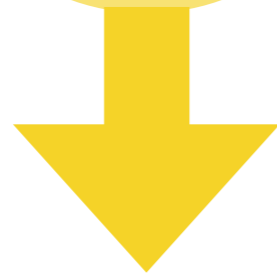
$$[\mathbb{1}_k \otimes \Phi](\rho) \geq 0$$

$$\Lambda_t = V_{t,s} \Lambda_s$$

k-positive

The dynamical map is k-divisible

$$\Lambda_t = V_{t,s} \Lambda_s$$

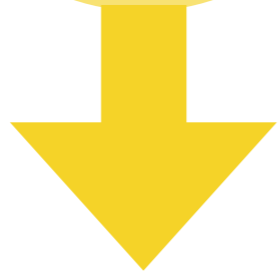


CP

k-positive for all
 $k = 1, 2, \dots$

The dynamical map is CP-divisible
(n -divisible)

$$\Lambda_t = V_{t,s} \Lambda_s$$



positive $k = 1$

The dynamical map is P-divisible

non-Markovianity degree

analogue to Schmidt number

$\text{NMD}[\Lambda_t] = k \iff \Lambda_t$ is $(n - k)$
but not $(n + 1 - k)$
divisible

$\text{NMD}[\Lambda_t] = 0$ **MARKOVIAN**

$\text{NMD}[\Lambda_t] = n$ **NON-MARKOVIAN**

non-Markovianity degree

analogue to Schmidt number

$$\mathcal{N}_k = \{ \Lambda_t \mid \text{NMD}[\Lambda_t] \leq k \}$$

$$\mathcal{N}_0 \subset \mathcal{N}_1 \subset \dots \subset \mathcal{N}_{n-1} \subset \mathcal{N}_n$$

Markovian maps

all dynamical maps

non-Markovianity degree

analogue to Schmidt number

$$\mathcal{N}_0 \subset \mathcal{N}_1 \subset \dots \subset \mathcal{N}_{n-1} \subset \mathcal{N}_n$$

Markovian maps

all dynamical maps

$$\mathcal{S}_1 \subset \mathcal{S}_2 \subset \dots \subset \mathcal{S}_n$$

separable states

all states

towards a hierarchy...

$$\mathcal{N}_0 \subset \mathcal{N}_1 \subset \dots \subset \mathcal{N}_{n-1} \subset \mathcal{N}_n$$

Markovian maps

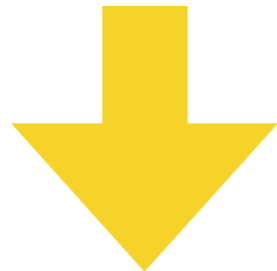
all dynamical maps

\mathcal{N}_{BLP}



Theorem

Λ_t **k-divisible**



$$\frac{d}{dt} \left\| \left[\mathbb{1}_k \otimes \Lambda_t \right] (X) \right\|_1 \leq 0$$

$$\forall X \in M_k \otimes \mathcal{B}(\mathcal{H})$$

$$\frac{d}{dt} \left\| [\mathbf{1}_k \otimes \Lambda_t](X) \right\|_1 \leq 0$$

 **special case**

$$\frac{d}{dt} \left\| \Lambda_t(X) \right\|_1 \leq 0$$

$$X = \rho_1 - \rho_2$$

BLP condition

towards a hierarchy...

$$\mathcal{N}_0 \subset \mathcal{N}_1 \subset \dots \subset \mathcal{N}_{n-1} \subset \mathcal{N}_n$$

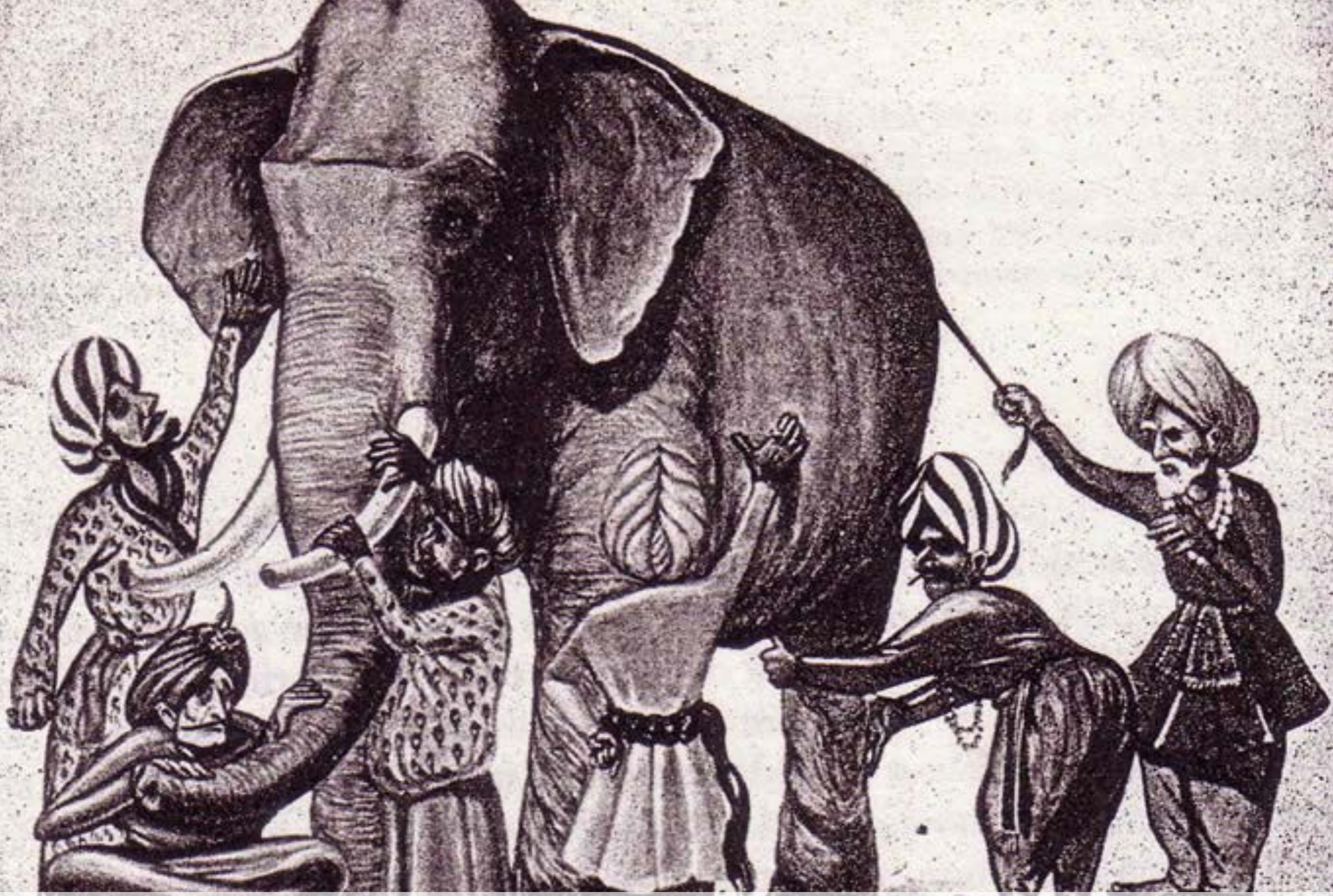
Markovian maps

\mathcal{N}_{BLP}

essentially non-Markovian maps



Is there a physical interpretation of non-Markovianity? Or are there many?



C. Addis, B. Bylicka, D. Chruściński and S. Maniscalco, "What we talk about when we talk about non-Markovianity", arXiv 1402.4975



Is non-Markovianity a
resource for quantum
technologies ?

ρ
input

quantum channel

Λ_t

$\rho(t)$
output

$t > t' > t''$

$\Lambda_{t''}$

$\Lambda_{t'}$



Λ_t





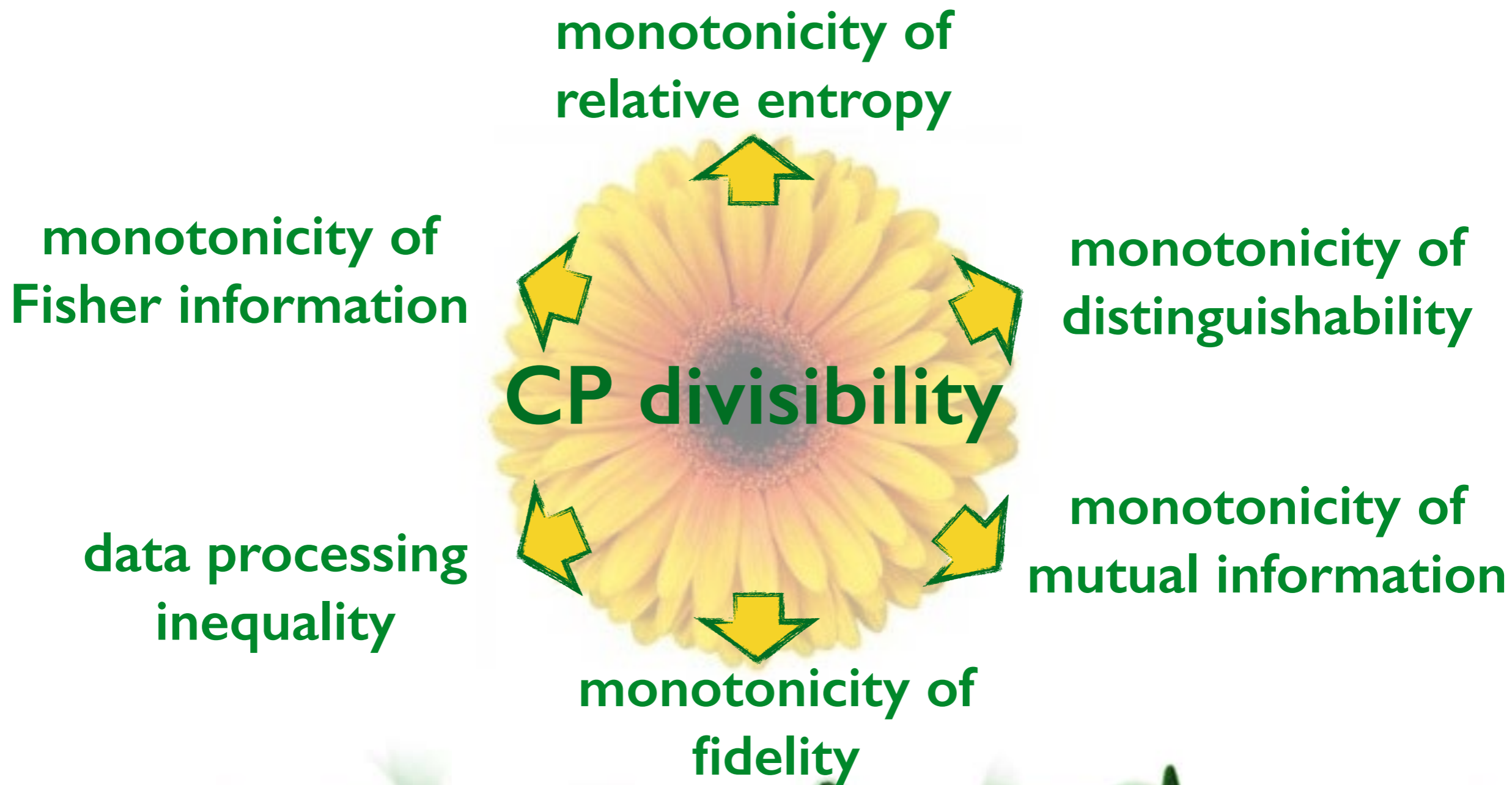
Quantum capacity

Bound on the maximum rate at which quantum information can reliably be transferred along a noisy quantum channel

$$Q(\Lambda_t) = \sup_{\rho} I_c(\rho, \Lambda_t)$$

$$I_c(\rho, \Lambda_t) = S(\Lambda_t \rho) - S(\rho, \Lambda_t)$$

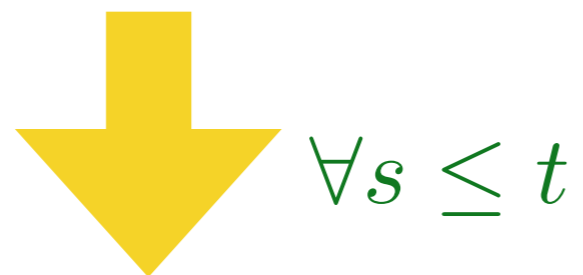
A common feature to all the measures



$$\rho \quad \Lambda_s \quad \rho(s)$$

$$\rho \quad \Lambda_t \quad \rho(t)$$

CP-divisibility



$$I_c(\rho, \Lambda_t) \leq I_c(\rho, \Lambda_s)$$

$$Q(\Lambda_t) \leq Q(\Lambda_s)$$

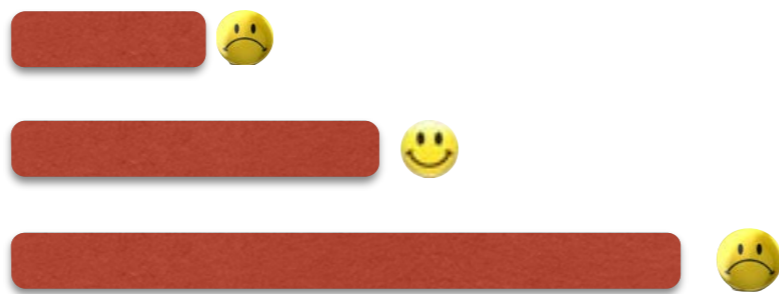
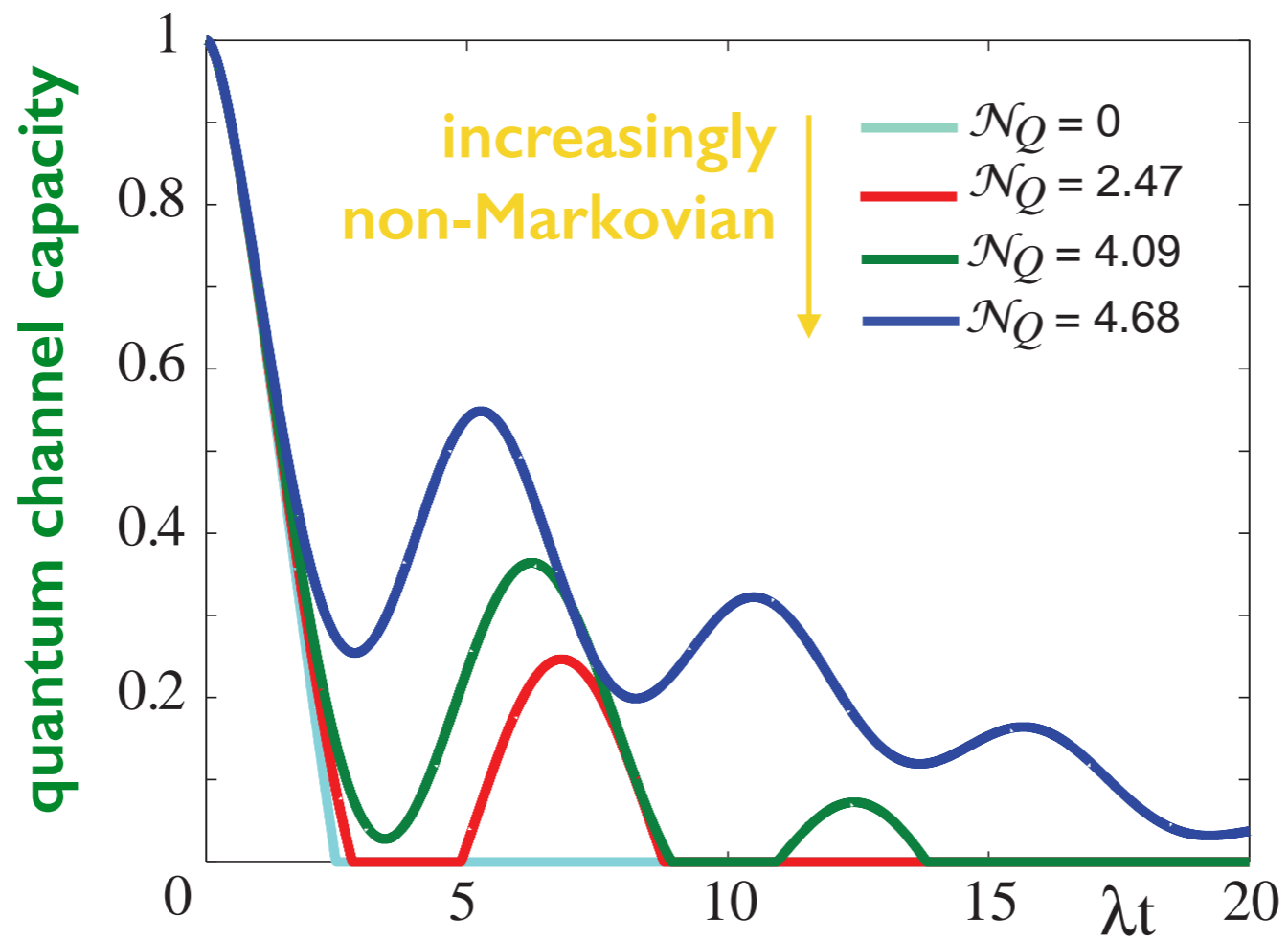
data processing inequality

How about non-Markovian maps?

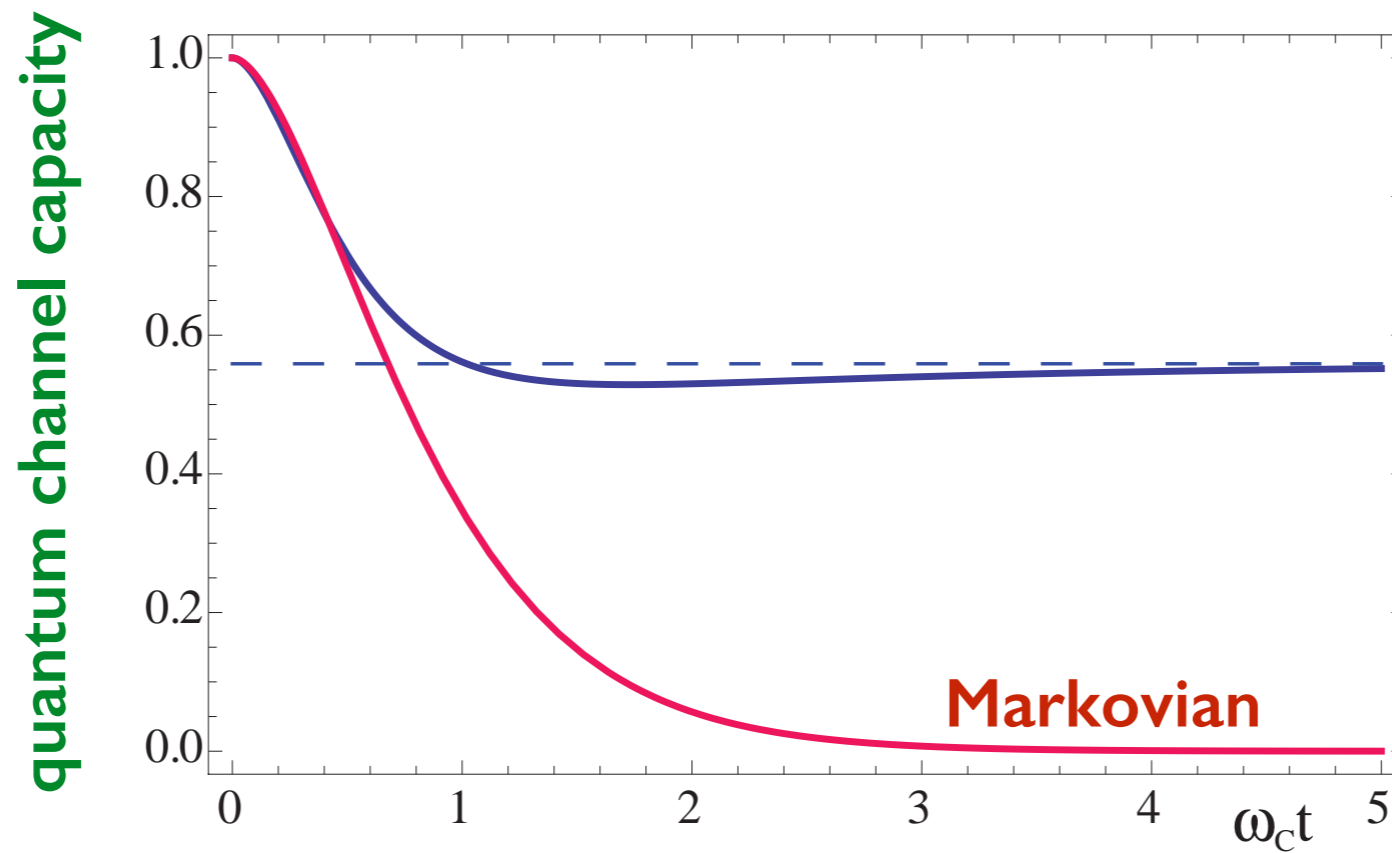
CP non-divisible



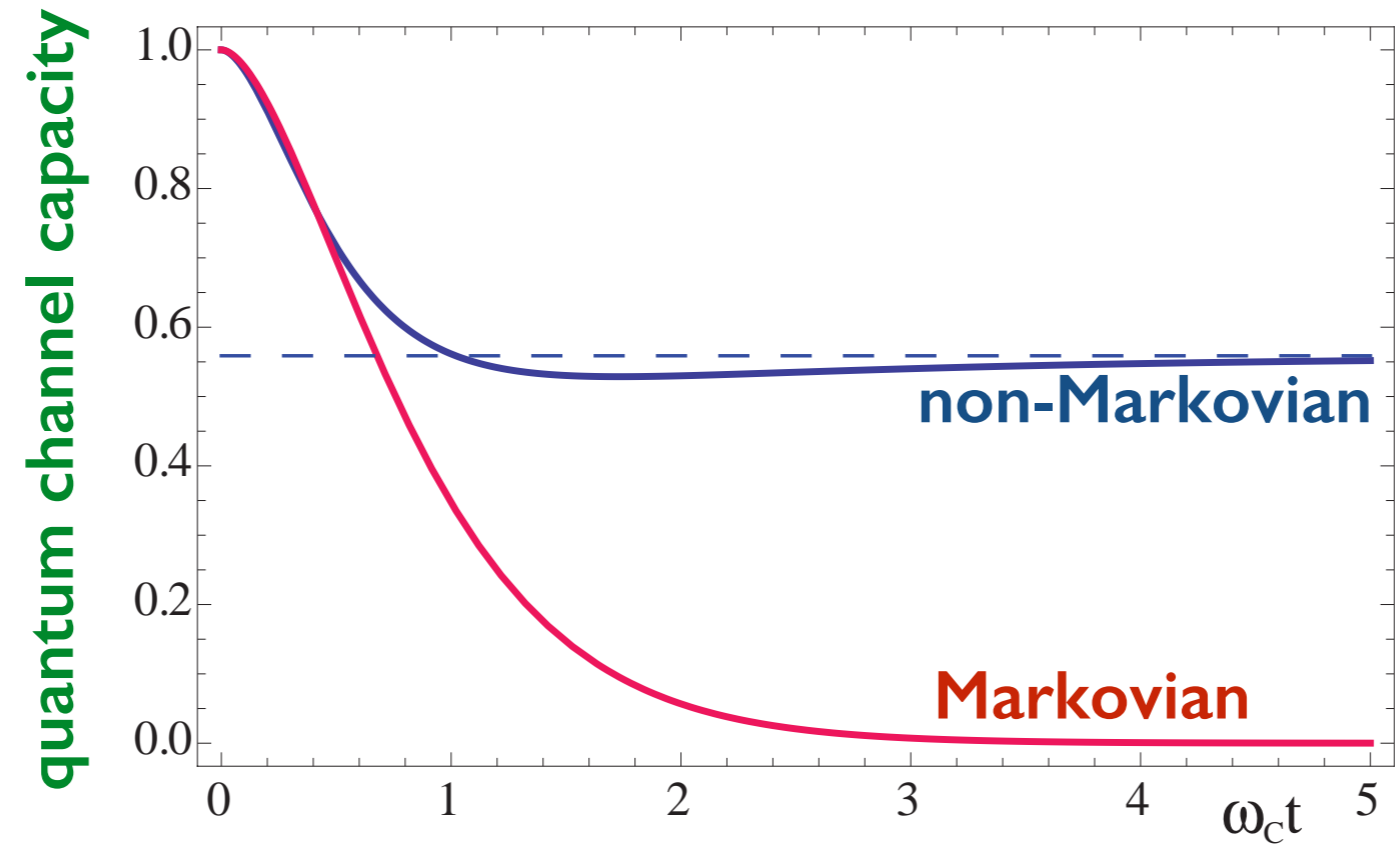
Exact amplitude damping channel



Exact dephasing channel



Exact dephasing channel





**Yes, but isn't most of what
is done in this field just
Rabi oscillations business
more or less?**

YES

NO

MAYBE



**What are the main
open problems of open
quantum systems
theory?**

Witnesses for non-Markovianity



Resource theory for non-Markovianity



Admissible physical CP maps





THANK
YOU









Entanglement assisted capacity

Bound on the maximum rate at which classical information can be reliably transferred along a noisy quantum channel, when Alice and Bob share unlimited entanglement

$$C_{ea}(\Lambda_t) = \sup_{\rho} I(\rho, \Lambda_t)$$

$$I(\rho, \Lambda_t) = S(\rho) + S(\Lambda_t \rho) - S(\rho, \Lambda_t)$$

$$\mathbb{1}_k \otimes \Phi \quad k = 1, 2, \dots$$

Φ is **k-positive** if

$\mathbb{1}_k \otimes \Phi$ is **positive**

$$L_t(\rho) = -i[H(t), \rho] + \sum_k \left(A_k(t) \rho A_k^\dagger(t) - \frac{1}{2} \{A_k^\dagger(t) A_k(t), \rho\} \right)$$

(Almost) **the most general form**
of master equation for open systems

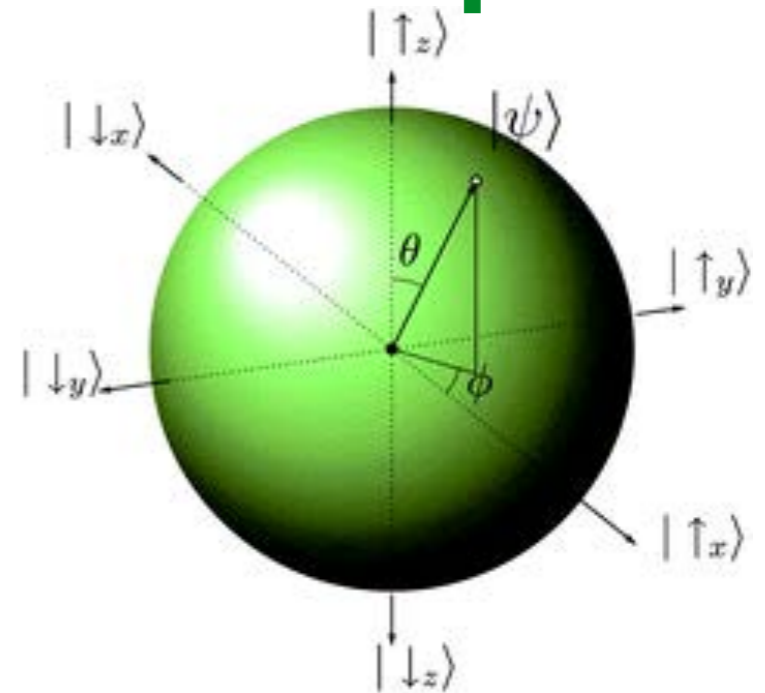
Example qubit dynamics

$$L_t = \frac{\gamma_+(t)}{2} ([\sigma_+, \rho \sigma_-] + [\sigma_+ \rho, \sigma_-]) \\ + \frac{\gamma_-(t)}{2} ([\sigma_-, \rho \sigma_+] + [\sigma_- \rho, \sigma_+])$$

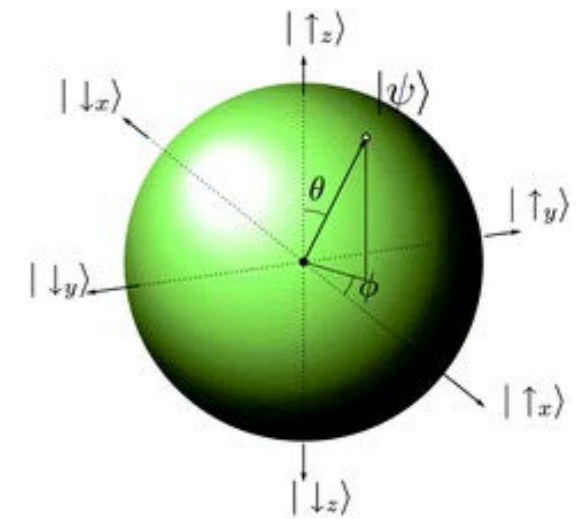
Bloch vector

$$x_k(t) = \text{Tr}[\sigma_k \Lambda_t(\rho)] \quad k = 1, 2, 3$$

Bloch sphere



Bloch vector dynamics



$$\frac{d}{dt} x_k(t) = -\frac{1}{T_{\perp}(t)} x_k(t), \quad k = 1, 2$$

TRANSVERSE RELAXATION TIME

$$T_{\perp}(t) = 2/[\gamma_{-}(t) + \gamma_{+}(t)]$$

$$\frac{d}{dt} x_3(t) = -\frac{1}{T_{\parallel}(t)} x_3(t) + [\gamma_{+}(t) - \gamma_{-}(t)]$$

LONGITUDINAL RELAXATION TIME

$$T_{\parallel}(t) = T_{\perp}(t)/2$$

TRANSVERSE RELAXATION TIME

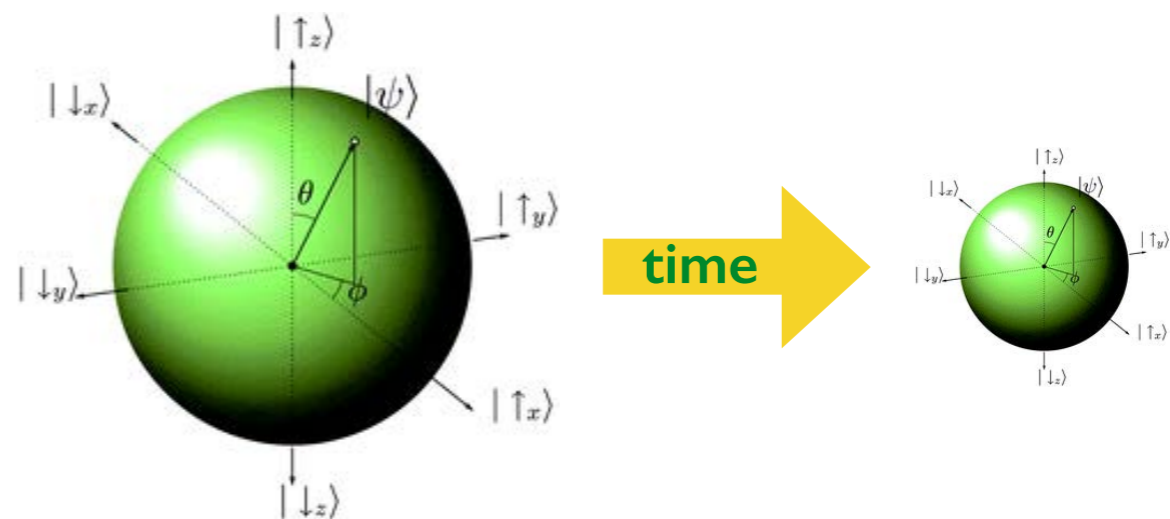
$$T_{\perp}(t) = 2/[\gamma_{-}(t) + \gamma_{+}(t)]$$

LONGITUDINAL RELAXATION TIME

$$T_{||}(t) = T_{\perp}(t)/2$$

P-divisibility = BLP Markovianity

$$T_{\perp}, T_{||}(t) \geq 0$$



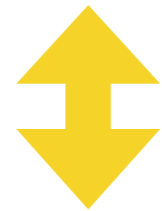
TRANSVERSE RELAXATION TIME

$$T_{\perp}(t) = 2/[\gamma_{-}(t) + \gamma_{+}(t)]$$

LONGITUDINAL RELAXATION TIME

$$T_{\parallel}(t) = T_{\perp}(t)/2$$

CP-divisibility



$$\gamma_{-}(t), \gamma_{+}(t) \geq 0$$