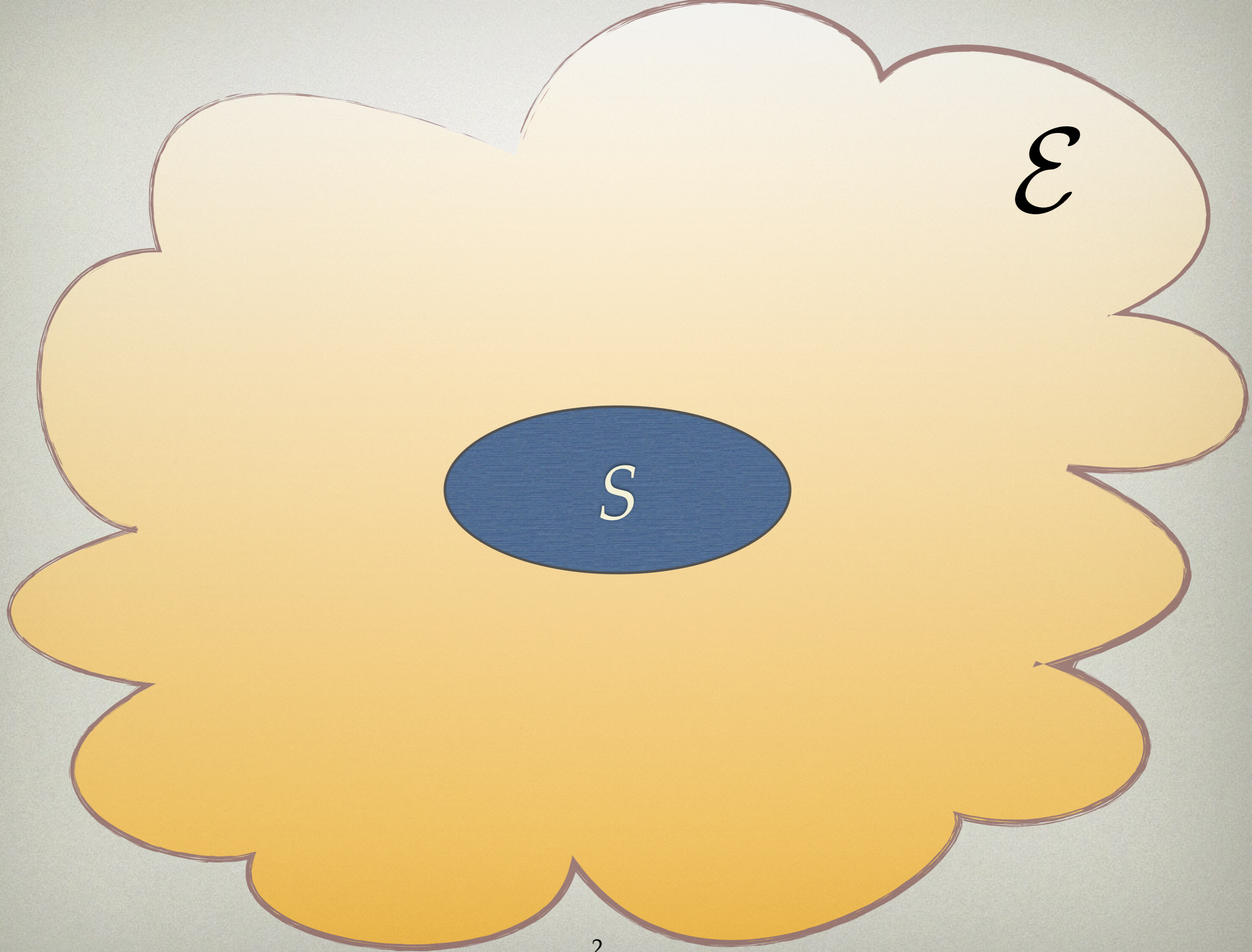


# NON-MARKOVIANITY THROUGH ACCESSIBLE INFORMATION

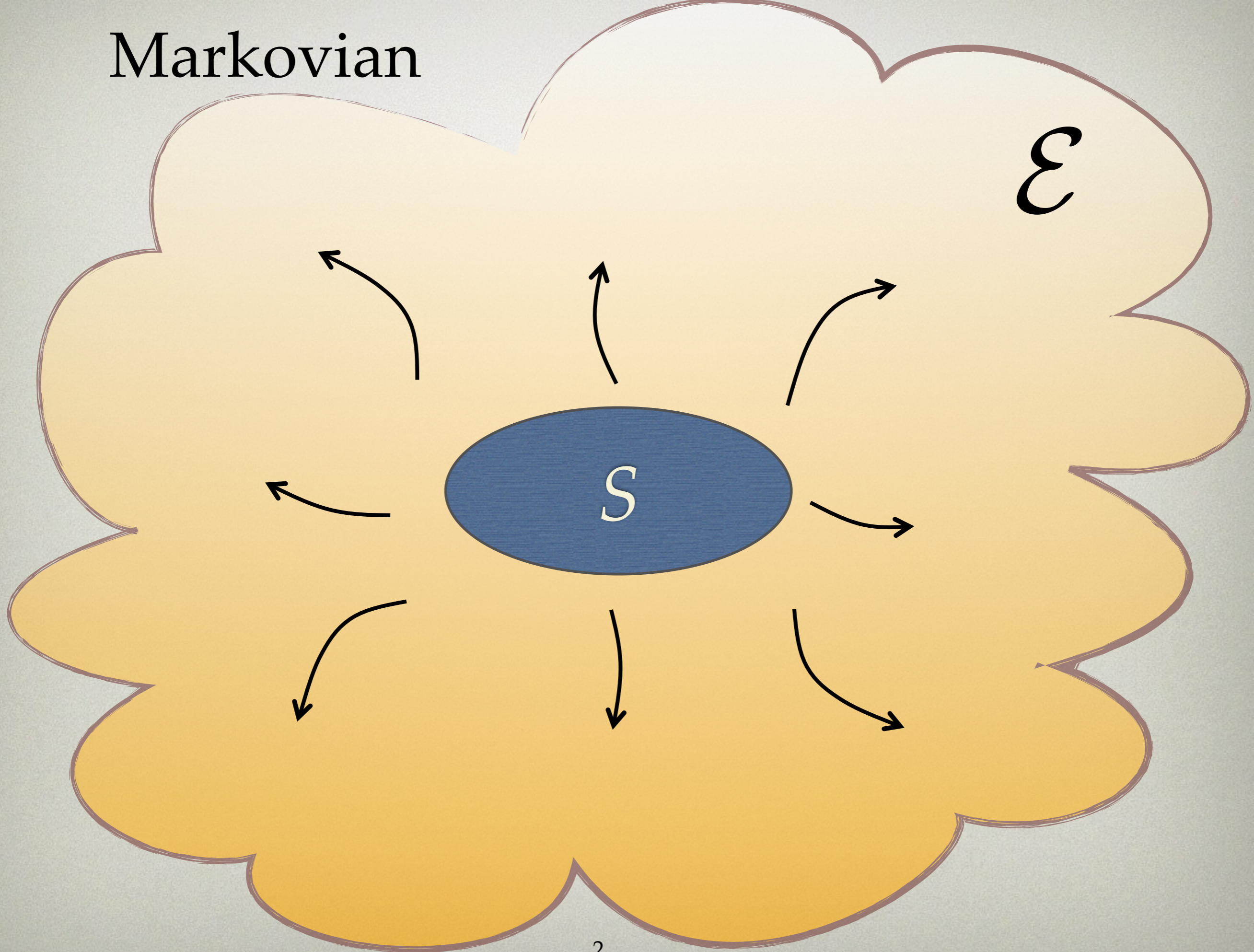
MARCOS C. DE OLIVEIRA  
STATE UNIVERSITY OF CAMPINAS (UNICAMP)  
SP, BRAZIL



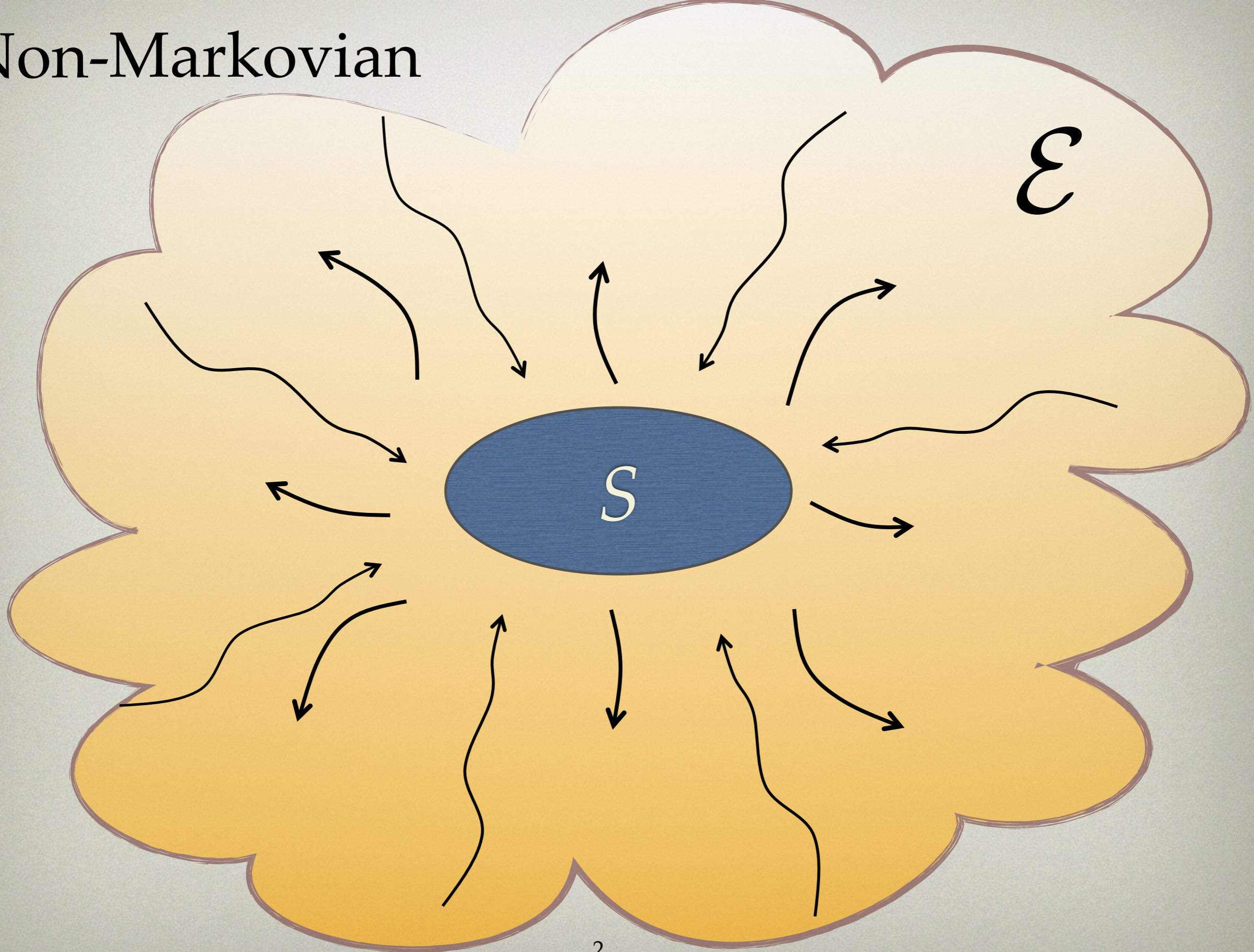
IICQI14 - 09- 2014



Markovian



# Non-Markovian



# OUTLINE

---

- Markovianity and Non-Markovianity
- Measuring the degree of non-Markovianity Breuer, Laine and Pilo measure
  - Breuer, Laine and Pilo measure
  - Rivas, Huega and Plenio measure
- Non-Markovianity through accessible information.
  - Theory
  - Experiment

# MARKOVIAN MASTER EQUATION

---

Lindblad form:

$$\frac{d\rho_s(t)}{dt} = -\frac{i}{\hbar}[H, \rho_s(t)] + \sum_k \gamma_k \left( 2L_k \rho_s(t) L_k^\dagger - \rho_s(t) L_k^\dagger L_k - L_k^\dagger L_k \rho_s(t) \right)$$

$\{\gamma_k\}$  : channel decay rate

$\{L_k\}$  : decay operator

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$\{\gamma_k\}$  : channel decay rate

$\{L_k\}$  : decay operator

Non-Markovian: cannot be written in the Lindblad form

# TIME-LOCAL MASTER EQUATION

---



# TIME-LOCAL MASTER EQUATION

---

$$\frac{\partial}{\partial t} \rho_s(t) = \mathcal{L}(t) \rho_s(t)$$

$$\mathcal{L}(t) \rho_s(t) = -\frac{i}{\hbar} [H(t), \rho_s(t)] + \sum_i \gamma_i(t) \left[ A_i(t) \rho_s(t) A_i(t)^\dagger - \frac{1}{2} \{ A_i(t)^\dagger A_i(t), \rho_s(t) \} \right]$$

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Dynamical map:  $\Lambda_{t,0} = T \exp \left[ \int_0^t \mathcal{L}(t') dt' \right]$

satisfies divisibility condition:  $\Lambda_{t_2,0} = \Lambda_{t_2,t_1} \Lambda_{t_1,0}$

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$$\gamma_i(t) < 0$$

CPTP

# NON-MARKOVIAN PROCESS

---

→ Environment correlation time

$$J(\omega) = \eta \frac{\omega^s}{\omega_c^{s-1}} \exp(-\omega/\omega_c)$$

$$\tau = 1/\omega_c$$

- 
- Backflow of information
  - Divisibility of the dynamical map
  - Non-monotonical behavior of entanglement
  - Non-monotonical behavior of mutual information

Breuer, Laine, and Piilo - PRL 103, 210401 (2009).

# BACKFLOW OF INFORMATION

*During a Markovian process the distinguishability of the system density matrix always reduce.*

Trace distance:

$$D_{12}(t) = \frac{1}{2} \text{Tr} \{ \rho_1(t) - \rho_2(t) \}$$

*In a non-Markovian process the distinguishability between the system density matrix increase for some instant of time.*

$$\frac{d}{dt} D_{12}(t) > 0$$

Breuer, Laine, and Piilo - PRL 103, 210401 (2009).

# BACKFLOW OF INFORMATION

Measure of non-Markovianity

$$\mathcal{N}_{BLP}(\Lambda) = \max_{\rho_1(0), \rho_2(0)} \int_{(dD_{12}(t)/dt) > 0} \frac{d}{dt} D_{12}(t) dt$$



maximum taken  
over all pairs of initial states

Breuer, Laine, and Piilo - PRL 103, 210401 (2009).



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*Information ?*

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# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

A quantum state in a Hilbert space  $H$

An arbitrary ancilla system in  $H^a$  is introduced:  $\rho^{sa} \in H \otimes H^a$

Quantum process  $\Lambda(t)$ :  $\rho^{sa}(t) = (\Lambda(t) \otimes I)\rho^{sa}$

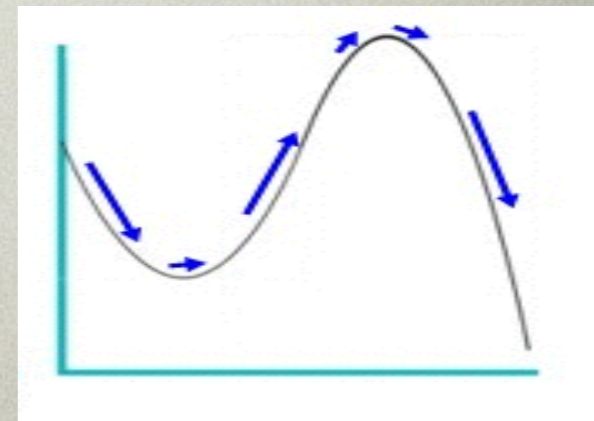
Since the entanglement shared by  $s$  and  $a$  is not increased by local operations, any entanglement measure has to monotonously decrease for all divisible processes.

$$\Lambda_{t_2,0} = \Lambda_{t_2,t_1} \Lambda_{t_1,0}$$

$E(\rho^{sa}(t))$  decays monotonically: Markovian

$d_t E(\rho^{sa}(t)) > 0$   Non-Markovian

Rivas, Huelga, and Plenio – PRL 105, 050403 (2010).



# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

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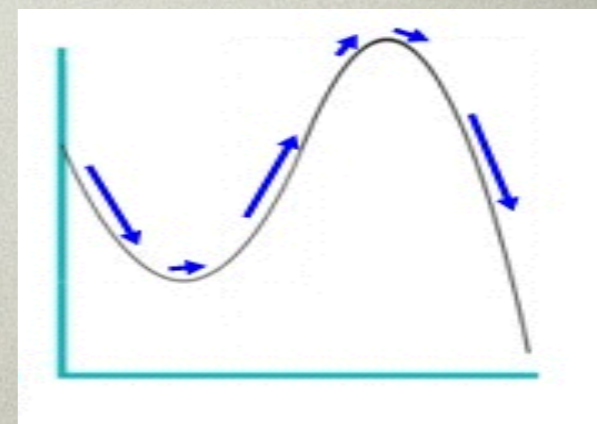
Since the entanglement shared by  $s$  and  $a$  is destroyed by local operations, any entanglement measure has to monotonously decrease for all divisible processes.

$$\Lambda_{t_2,0} = \Lambda_{t_2,t_1} \Lambda_{t_1,0}$$

$E(\rho^{sa}(t))$  decays monotonically: Markovian

$d_t E(\rho^{sa}(t)) > 0$   Non-Markovian

Rivas, Huelga, and Plenio – PRL 105, 050403 (2010).



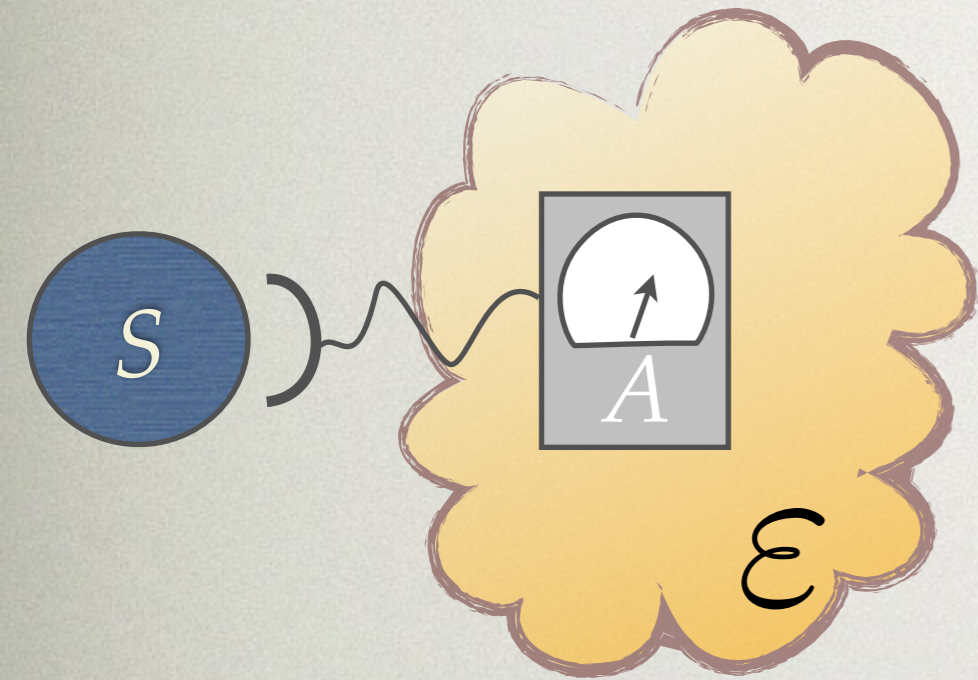
*Why?*

# ACCESSIBLE INFORMATION

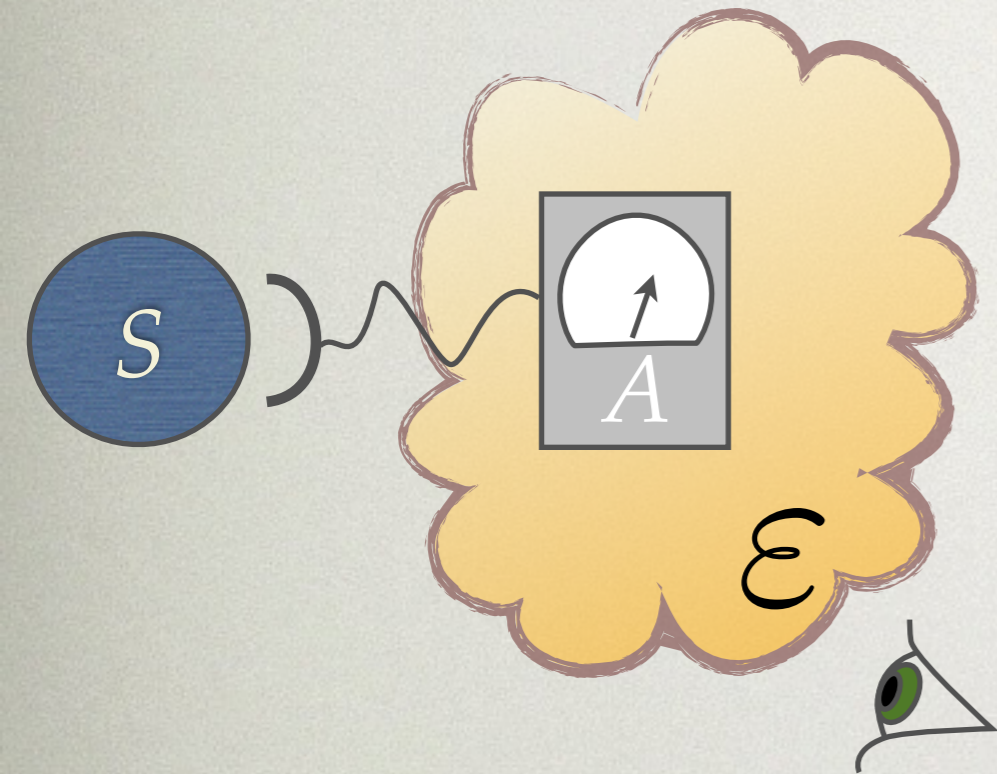


S

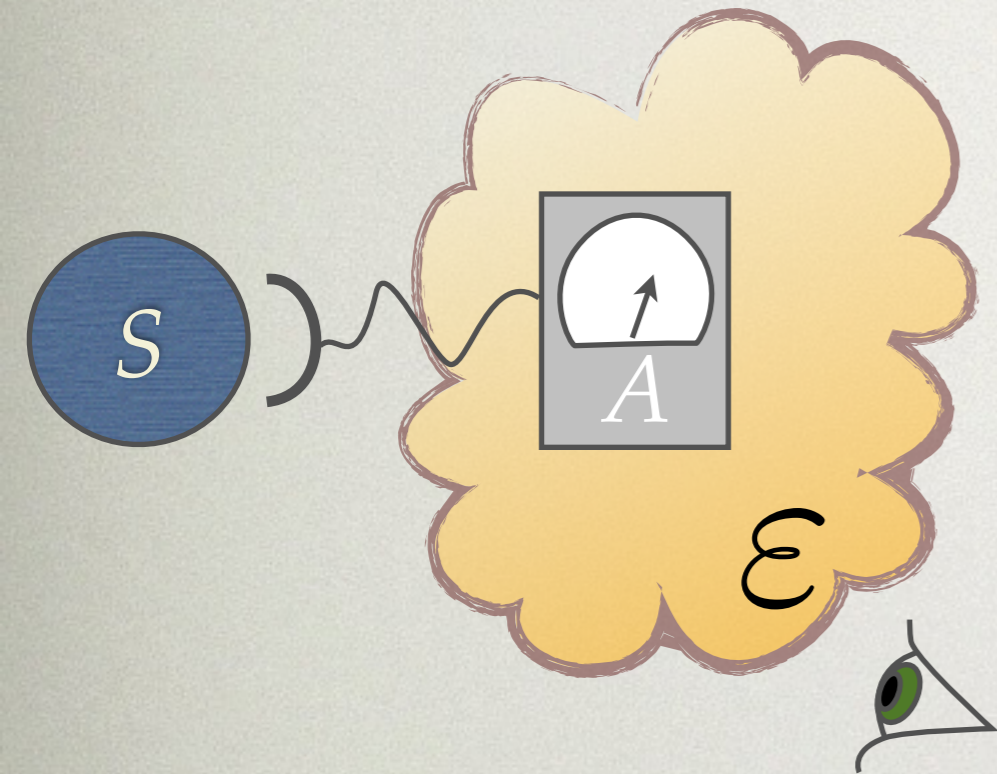
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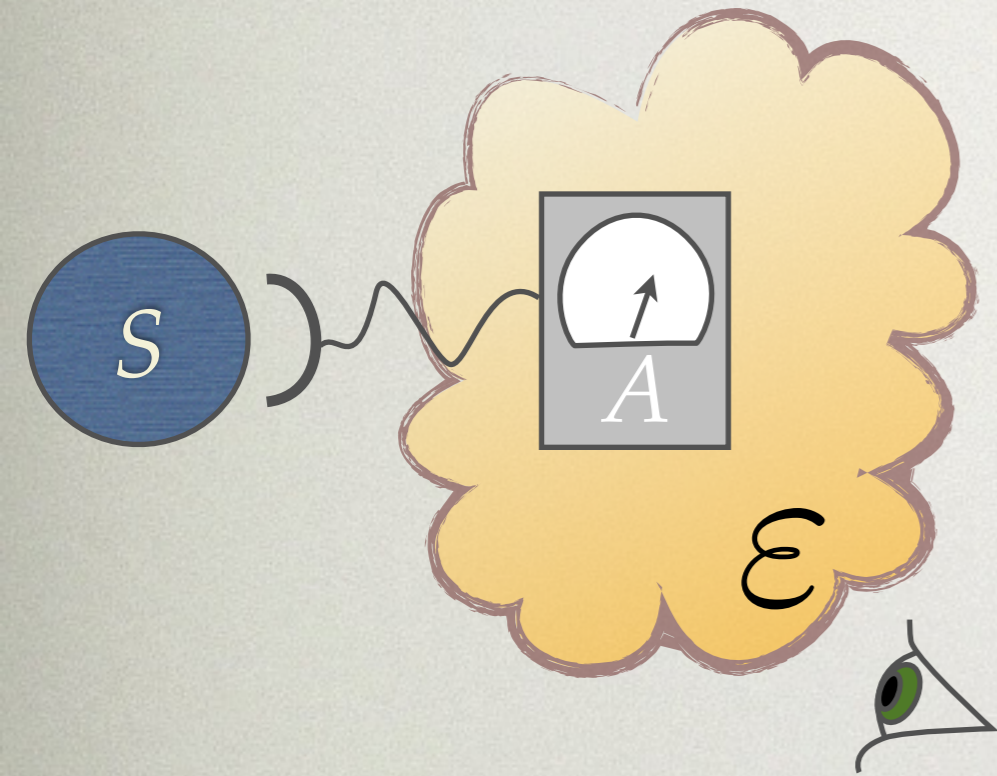


$$J_{S\mathcal{E}}^{\leftarrow} = S(\rho_S) - \sum_i p_i S(\rho_{S|i})$$

$$\rho_{S|i} = \frac{\text{Tr}_{\mathcal{E}}\{\Gamma_i^{\mathcal{E}} \rho_{S\mathcal{E}} \Gamma_i^{\mathcal{E}\dagger}\}}{p_i}$$

$$p_i = \text{Tr}\{\Gamma_i^{\mathcal{E}\dagger} \Gamma_i^{\mathcal{E}} \rho_{S\mathcal{E}}\}$$

# ACCESSIBLE INFORMATION



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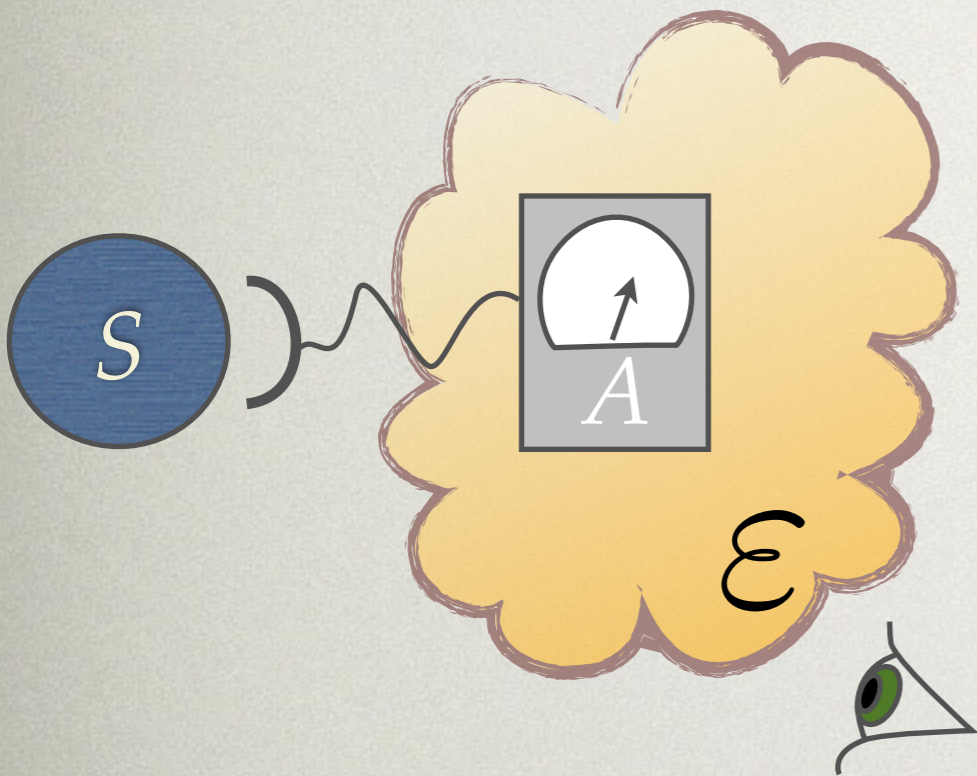
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Depends on chosen  $\{\Gamma_i^{\mathcal{E}}\}$



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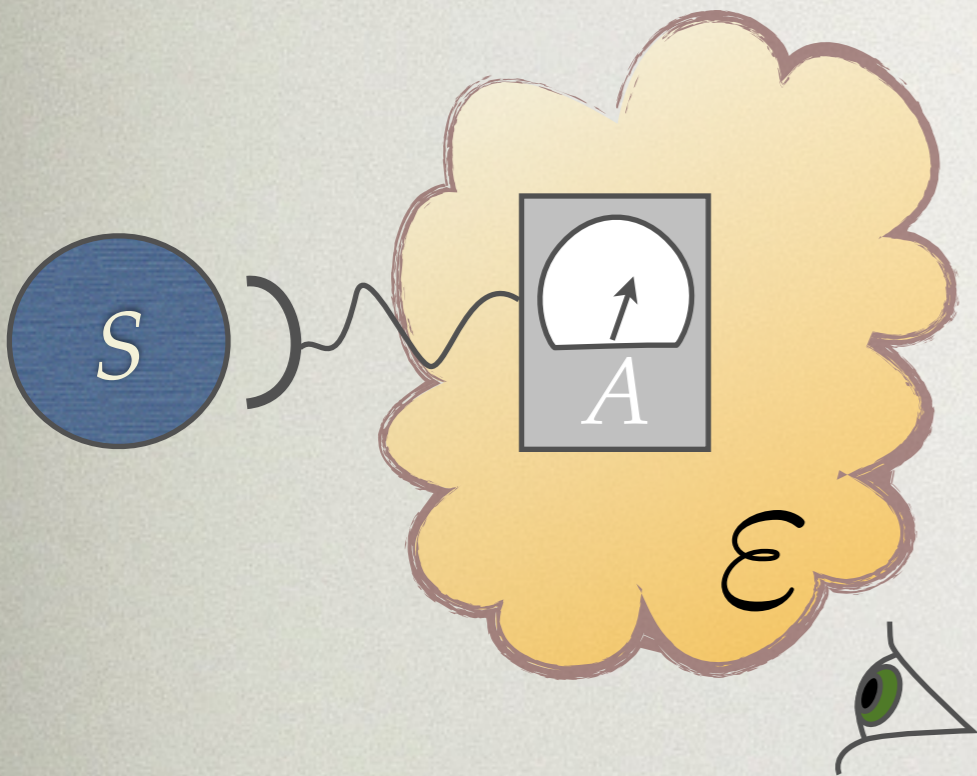
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Depends on chosen  $\{\Gamma_i^{\mathcal{E}}\}$

$$J_{S\mathcal{E}}^{\leftarrow} = \max_{\{\Gamma_i^{\mathcal{E}}\}} \left[ S(\rho_S) - \sum_i p_i S(\rho_{S|i}) \right]$$

Classical Correlation

# ACCESSIBLE INFORMATION



$$J_{S\mathcal{E}}^{\leftarrow} = S(\rho_S) - \sum_i p_i S(\rho_{S|i})$$

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Classical Correlation

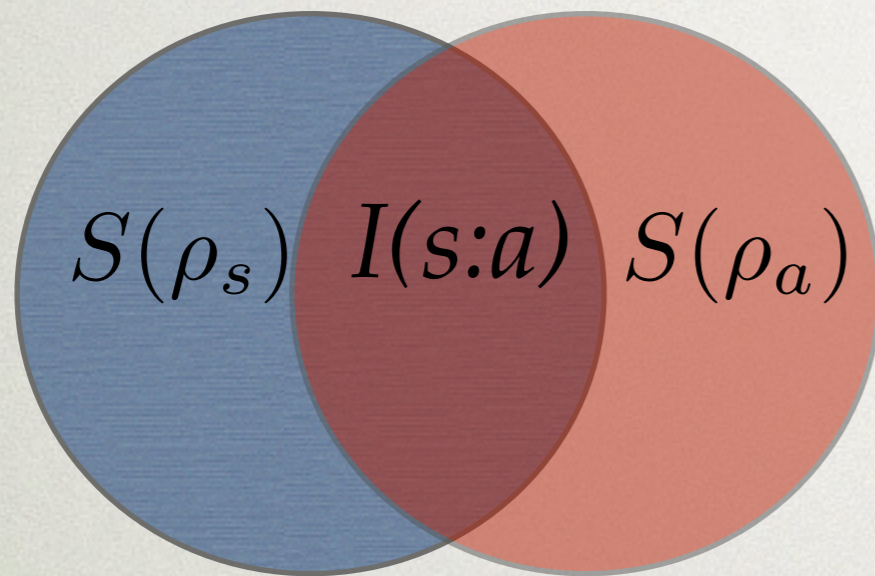
$$J_{S\mathcal{E}}^{\leftarrow} = S(\rho_S) - E_{SA}$$

# ACCESSIBLE INFORMATION

$$J_{S\mathcal{E}}^{\leftarrow} = S(\rho_S) - E_{S\mathcal{A}}$$

# LOCAL ACCESSIBLE AND INACCESSIBLE INFORMATION

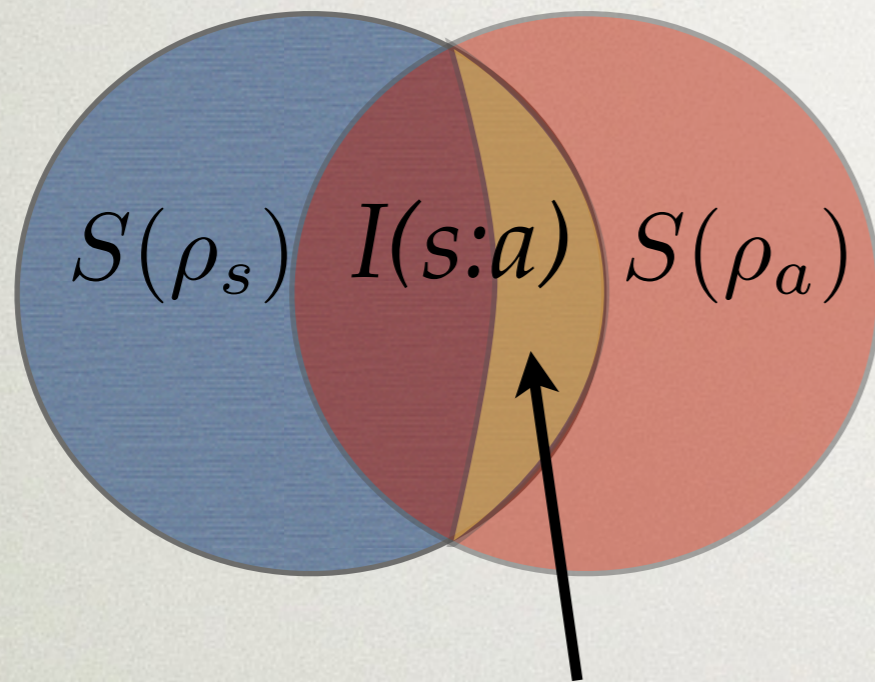
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$$I(s : a) = S(\rho_s) + S(\rho_a) - S(\rho_{sa})$$

# LOCAL ACCESSIBLE AND INACCESSIBLE INFORMATION

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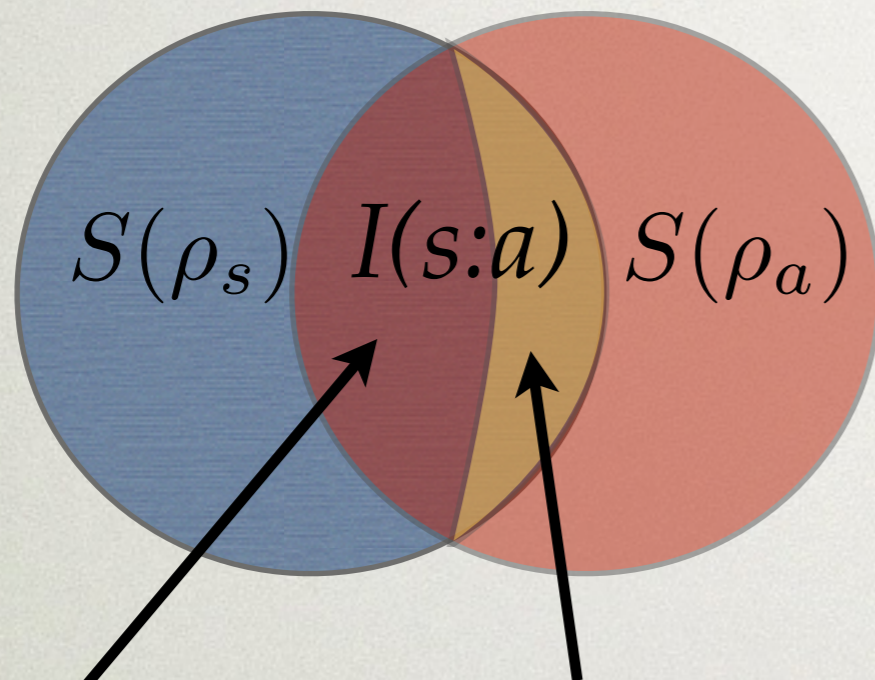


$$I(s : a) = S(\rho_s) + S(\rho_a) - S(\rho_{sa})$$

$$J_{s|a}^{\max}(\rho_{sa}) = \max_{\{\Gamma_i^a\}} \left[ S(\rho_s) - \sum_i p_i S(\rho_s^i | \Gamma_i^a) \right] \quad (\text{C.C.})$$

# LOCAL ACCESSIBLE AND INACCESSIBLE INFORMATION

---



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$$\delta_{AB}^{\leftarrow} = I_{AB} - J_{AB}^{\leftarrow} \quad (\text{Quantum Discord})$$

# SOME RESULTS

PHYSICAL REVIEW A **84**, 012313 (2011)

## Conservation law for distributed entanglement of formation and quantum discord

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(Received 30 August 2010; revised manuscript received 3 May 2011; published 13 July 2011)

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PRL **107**, 020502 (2011)

PHYSICAL REVIEW LETTERS

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8 JULY 2011

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PHYSICAL REVIEW LETTERS

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**New Journal of Physics**  
The open-access journal for physics

## Locally inaccessible information as a fundamental ingredient to quantum information

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and M C de Oliveira<sup>3,4,5</sup>

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## Non-Markovianity through accessible information

F. F. Fanchini,<sup>1,\*</sup> G. Karpat,<sup>1</sup> B. Çakmak,<sup>2</sup> L. K. Castelano,<sup>3</sup> G. H. Aguilar,<sup>4</sup> O.  
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<sup>2</sup>Faculty of Engineering and Natural Sciences, Sabanci University, Tuzla, Istanbul, 34956, Turkey

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PRL **112**, 210402 (2014) **arXiv:1402.5395**

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## Non-Markovianity through accessible information

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# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

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$$E_{SA} = S(\rho_S) - J_{SE}^{\leftarrow}$$

# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

---

$$\frac{d}{dt} E_{S\mathcal{A}} = \frac{d}{dt} S(\rho_S) - \frac{d}{dt} J_{S\mathcal{E}}^{\leftarrow}$$

# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

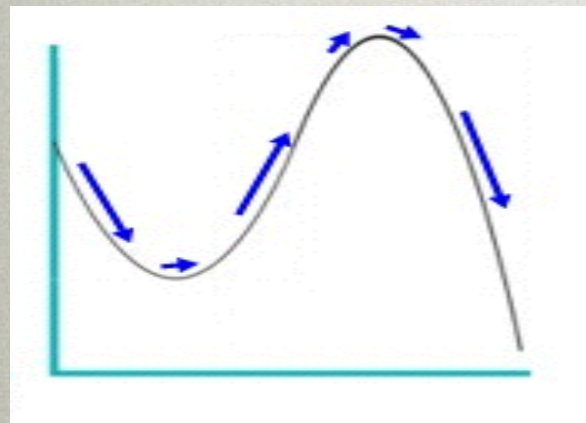
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# NON-MONOTONICAL BEHAVIOR OF ENTANGLEMENT

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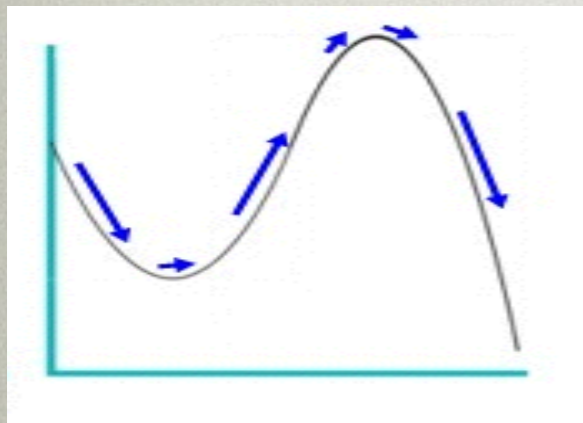
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→ *backflow of information*

$$\mathcal{N}(\Lambda) \equiv \max_{\rho_{SA}(0)} \int_{(d/dt)E_{SA} > 0} \frac{d}{dt} E_{SA}(t) dt$$

# SIMPLIFICATION

Since:

- System  $S$  does not interact with the environment,
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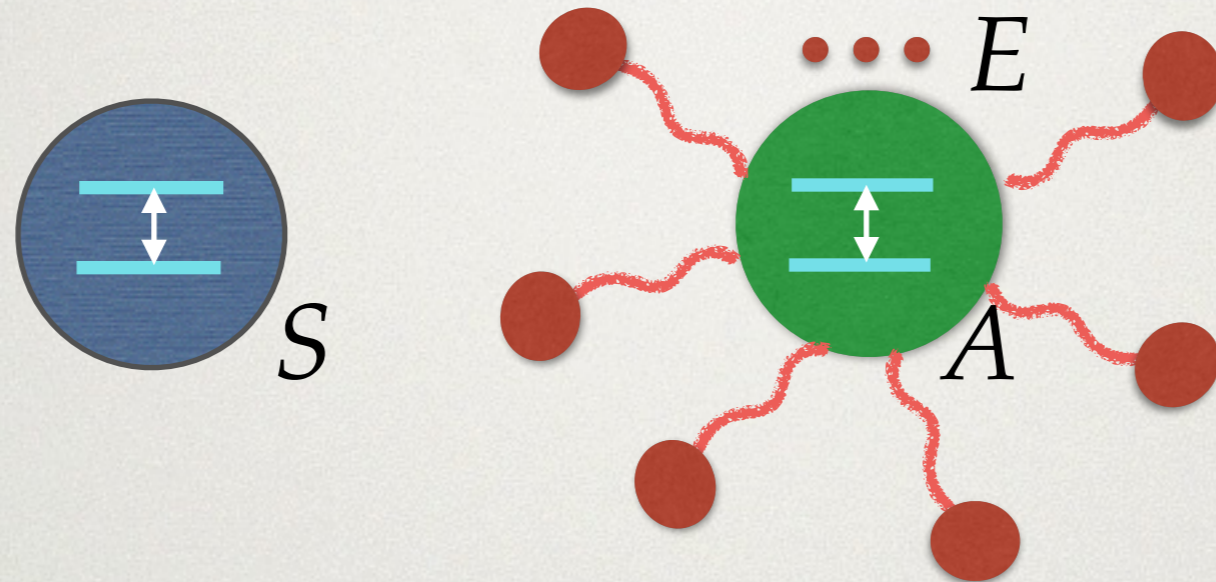
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# EXAMPLE



$$H_{\mathcal{AE}} = \omega_0 \sigma_+ \sigma_- + \sum_k \omega_k a_k^\dagger a_k + (\sigma_+ B + \sigma_- B^\dagger)$$

$$B = \sum_k g_k a_k$$

$$J(\omega) = \frac{1}{2\pi} \frac{\gamma_0 \lambda^2}{(\omega_0 - \omega)^2 + \lambda^2}$$

$\gamma_0$  : related to the system reservoir coupling

$\tau_R$  : system relaxation time

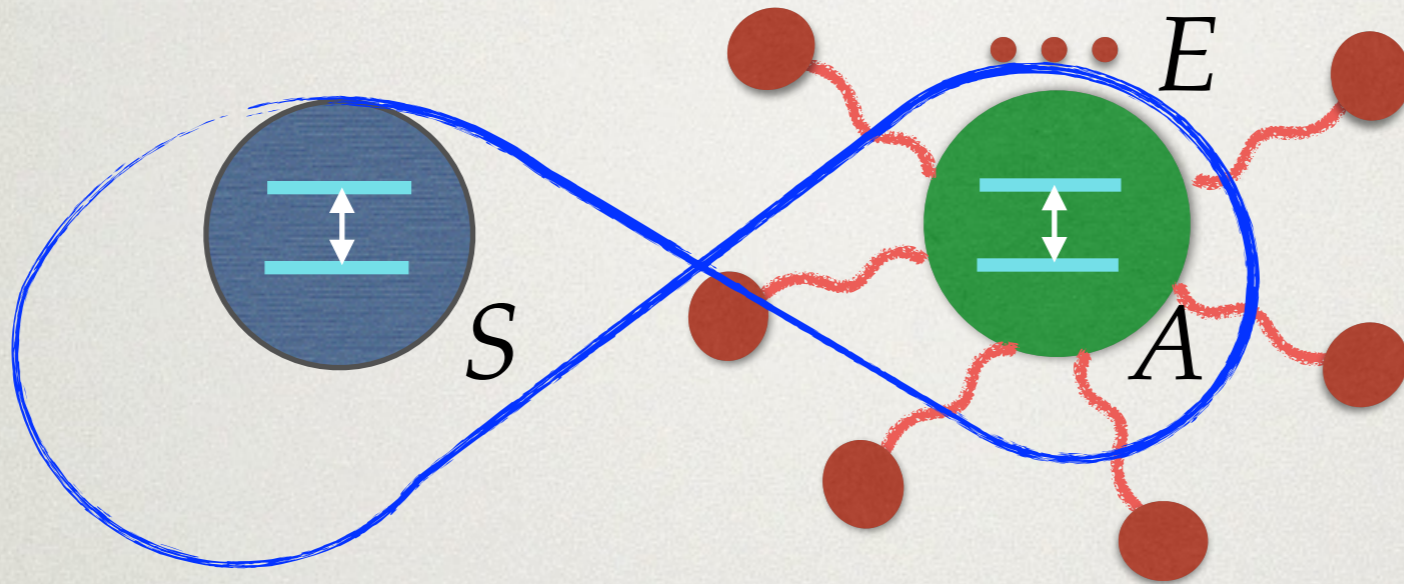
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# TIME-LOCAL MASTER EQUATION

$$\frac{\partial}{\partial t} \rho_{\mathcal{A}}(t) = \gamma(t) \left( \sigma_- \rho_{\mathcal{A}}(t) \sigma_+ - \frac{1}{2} \{ \sigma_+ \sigma_-, \rho_{\mathcal{A}}(t) \} \right)$$

$$\gamma(t) = \frac{2\gamma_0 \lambda \sinh(dt/2)}{d \cosh(dt/2) + \lambda \sinh(dt/2)}, \quad d = \sqrt{\lambda^2 - 2\gamma_0 \lambda}$$

$$\rho(t) = \Lambda(\rho(0)) = \sum_{i=1}^2 M_i(t) \rho(0) M_i^\dagger(t) \quad \leftarrow \text{Solution}$$

$$M_1(t) = \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{1-p(t)} \end{pmatrix}, \quad M_2(t) = \begin{pmatrix} 0 & \sqrt{p(t)} \\ 0 & 0 \end{pmatrix},$$

$$p(t) = 1 - e^{-\lambda t} \left[ \cosh\left(\frac{dt}{2}\right) + \frac{\lambda}{d} \sinh\left(\frac{dt}{2}\right) \right]^2$$

# OPTIMIZATION

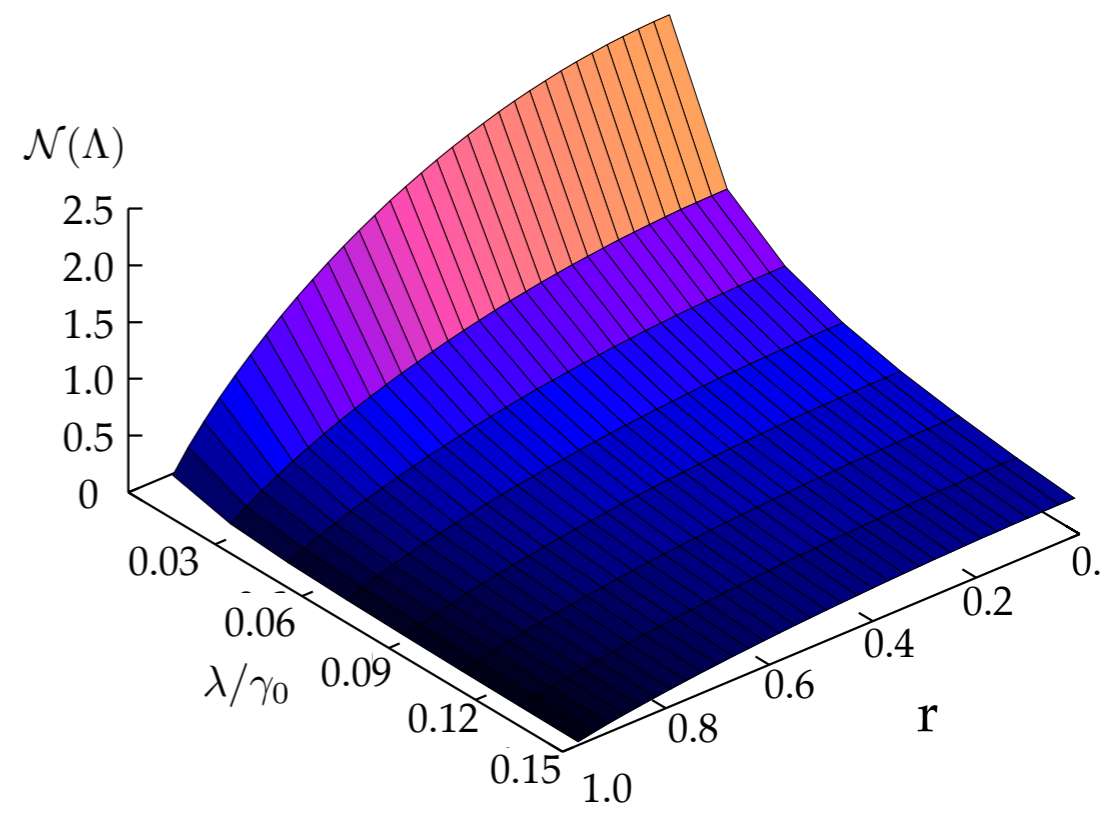
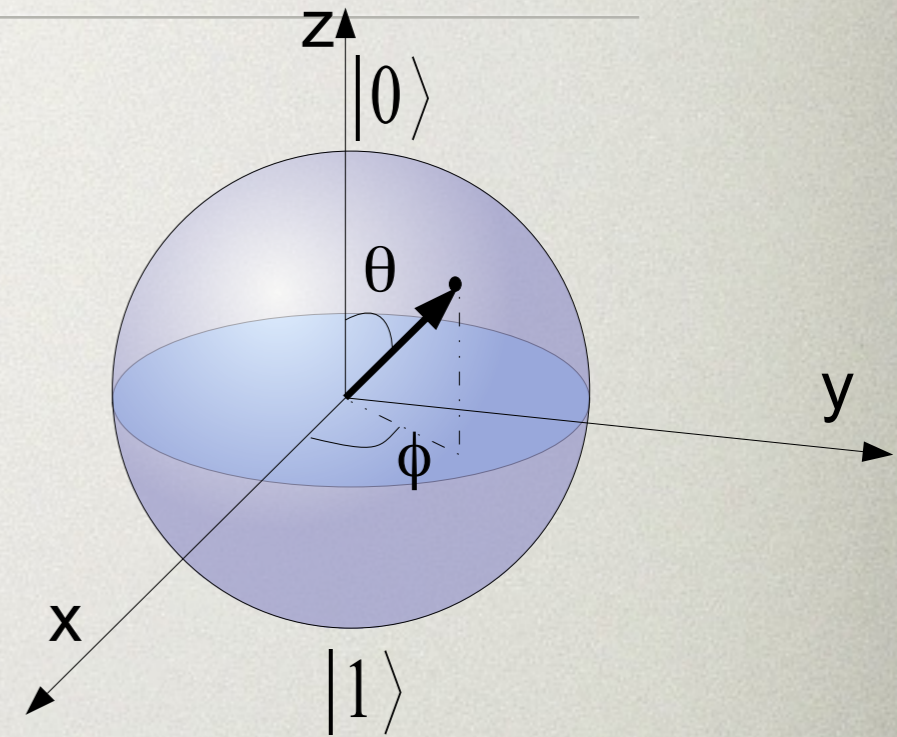
?

$$\rho_A = \frac{1}{2}(I + \vec{r} \cdot \vec{\sigma})$$

$$\vec{r} = (r \sin \theta \cos \phi, r \sin \theta \sin \phi, r \cos \theta)$$

$\mathcal{N}(\Lambda)$  is independent of  $\theta$  and  $\phi$

The optimal state is the maximally mixed state



# OPTIMIZATION

$$\mathcal{N}(\Lambda) \equiv \max_{\rho_{\mathcal{A}}(0)} \int_{(d/dt)E_{\mathcal{S}\mathcal{A}} > 0} \frac{d}{dt} E_{\mathcal{S}\mathcal{A}}(t) dt$$

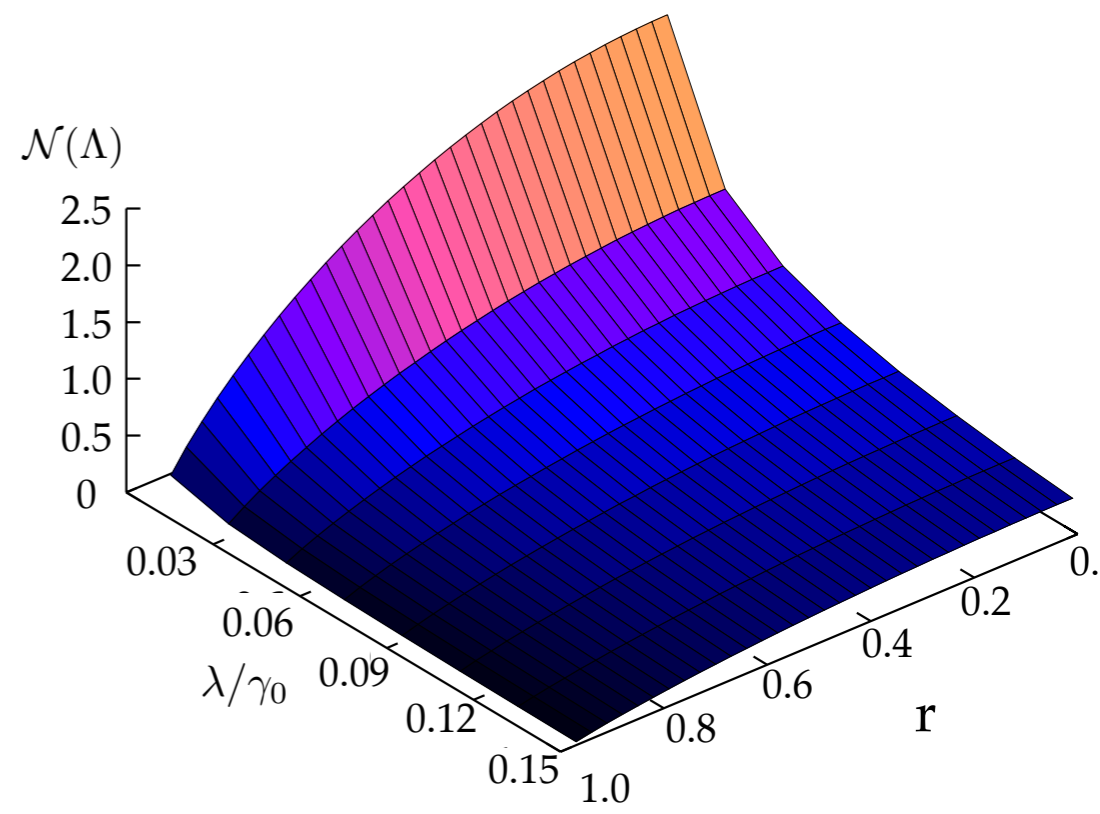
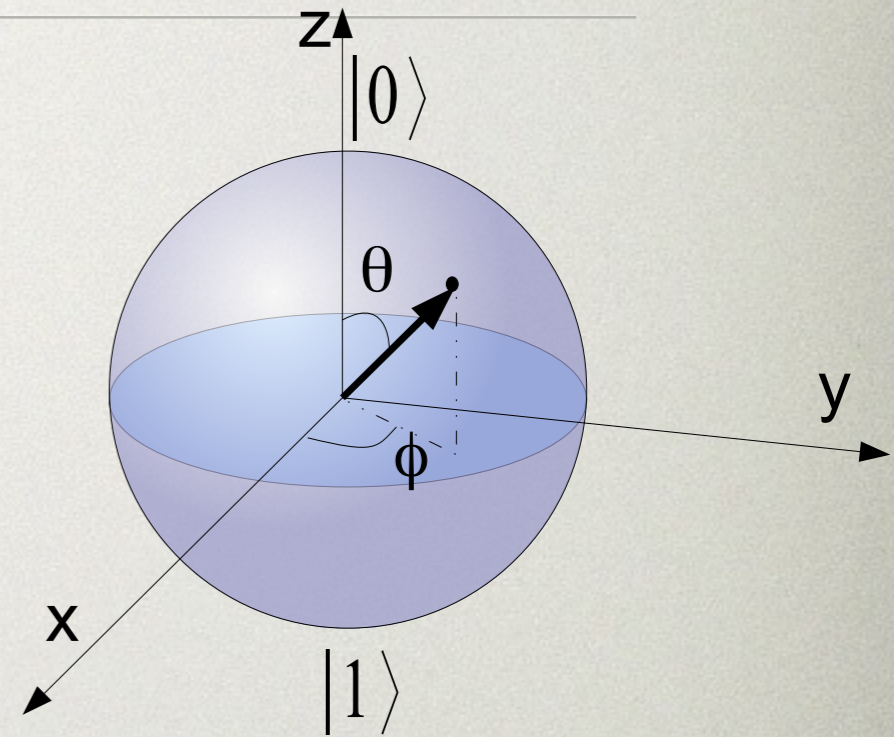
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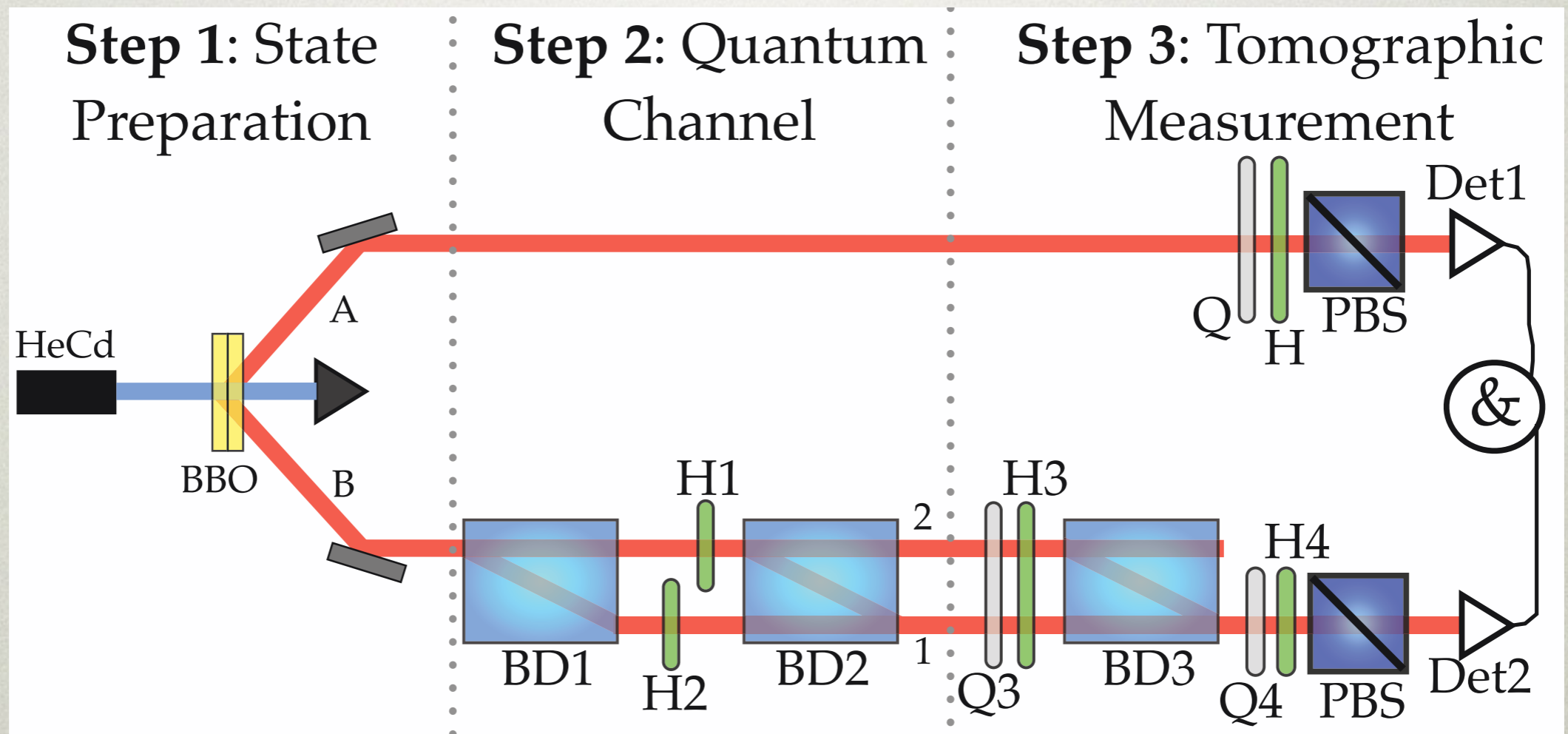
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# EXPERIMENT



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We assume the following tripartite state :

$$|\Psi(0)\rangle_{S\mathcal{A}\mathcal{E}} = \sqrt{\frac{1}{2}} [ |10\rangle + |01\rangle ]_{S\mathcal{A}} |0\rangle_{\mathcal{E}}$$

As a result of the interaction between  $A$  and  $E$ , the state  $SA$  evolves into

$$\rho_{S\mathcal{A}}(t) = \frac{1}{2} |\phi_{S\mathcal{A}}(t)\rangle \langle \phi_{S\mathcal{A}}(t)| + \frac{1}{2} p(t) |00\rangle \langle 00|$$

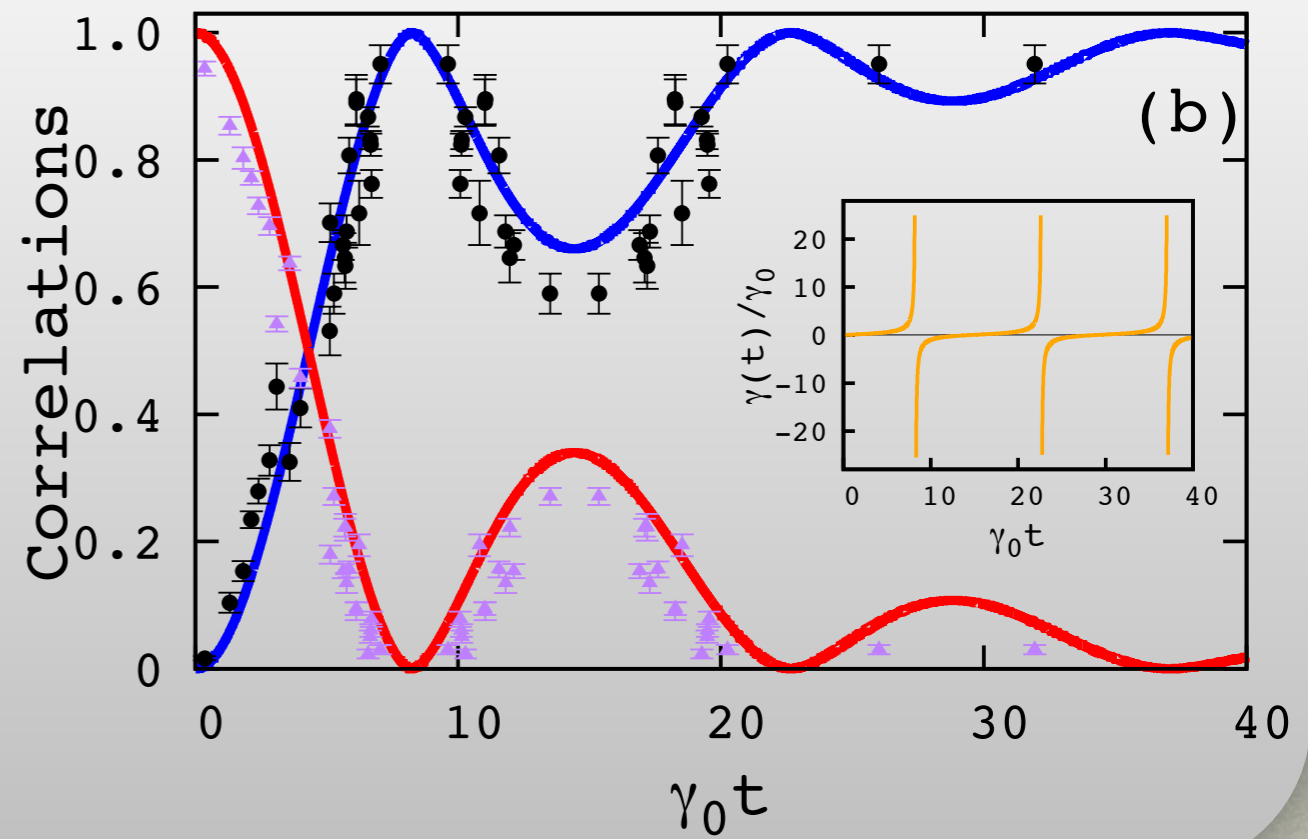
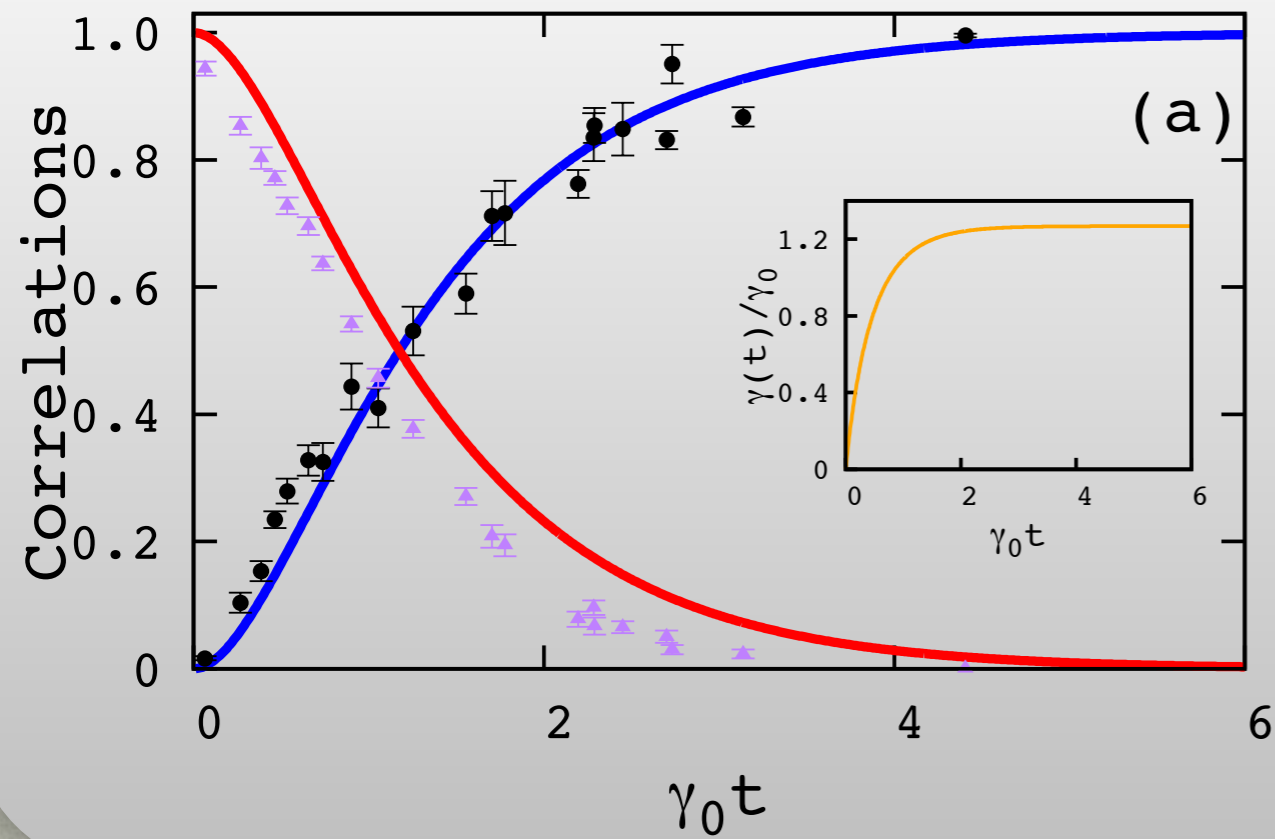
$$|\phi_{S\mathcal{A}}(t)\rangle = |10\rangle + \sqrt{1 - p(t)} |01\rangle$$

and the state of  $SE$  evolves into

$$\rho_{S\mathcal{E}}(t) = \frac{1}{2} |\psi_{S\mathcal{E}}(t)\rangle \langle \psi_{S\mathcal{E}}(t)| + \frac{1}{2} [1 - p(t)] |00\rangle \langle 00|$$

$$|\psi_{S\mathcal{E}}(t)\rangle = |10\rangle + p(t) |01\rangle$$

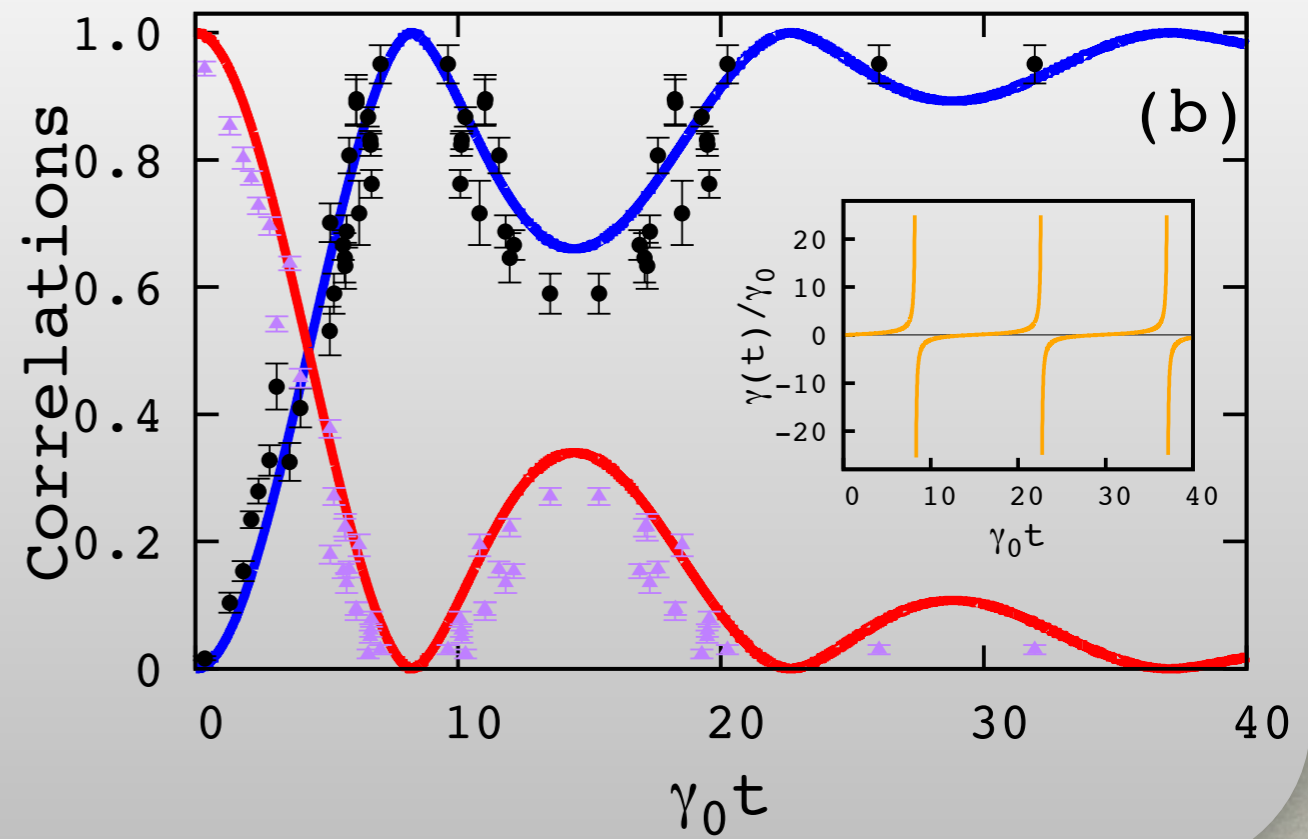
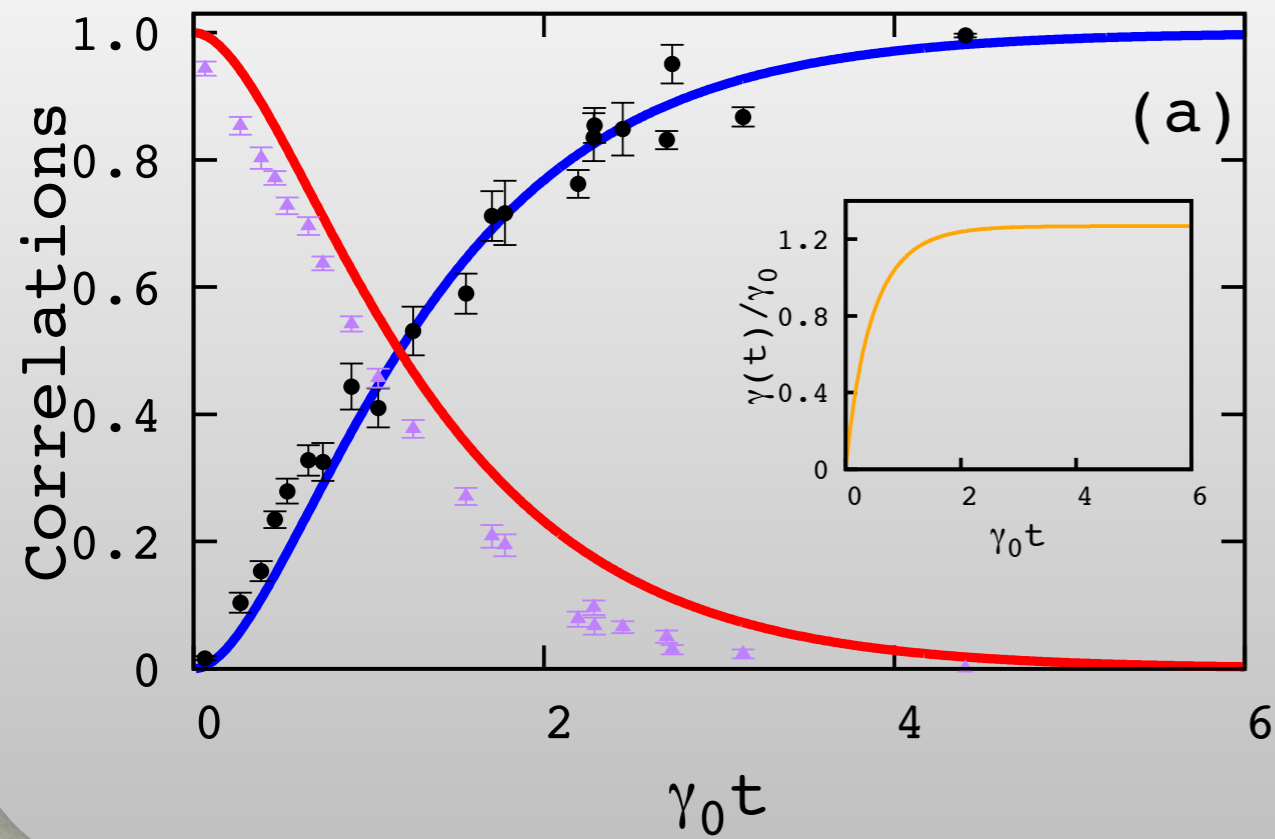
# RESULTS



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# RESULTS



—  $E_{SA}$   
 —  $J_{SE}^{\leftarrow}$

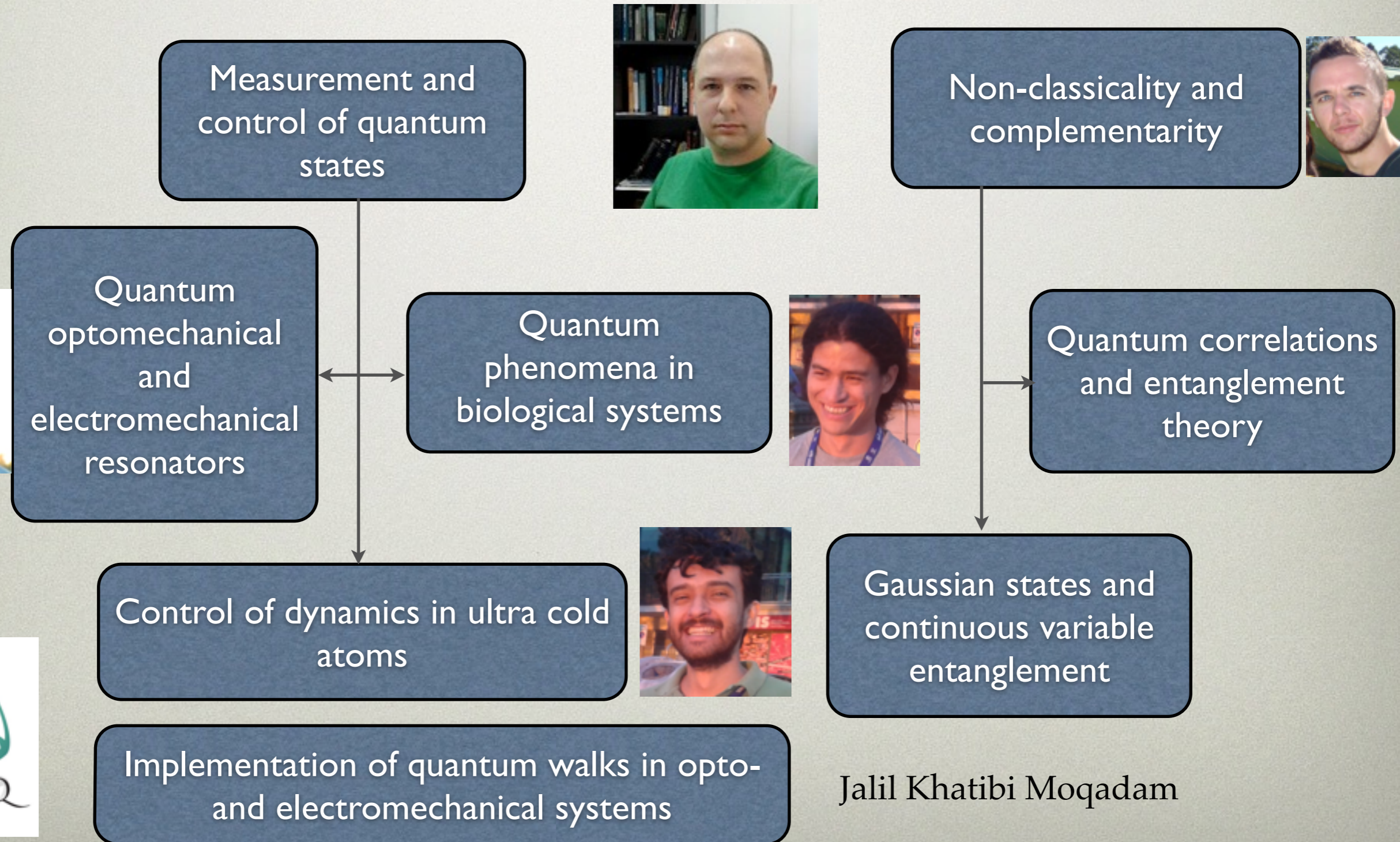
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# CONCLUSIONS

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- Simplified and computable measure of non-Markovianity
- Interpretation in terms of flow of information (measured by the classical correlation)
- Experimental demonstration using an optical setup

# QUANTUM INFORMATION THEORY



Jalil Khatibi Moqadam