

Quantum Metrology

in open quantum systems

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Parameter estimation



This yields **ERROR**

classical estimation

unbiased estimator: $\langle E(x_1, \dots, x_N) \rangle_\lambda = \lambda$

$$\Delta E = E(x_1, \dots, x_N) - \langle E(x_1, \dots, x_N) \rangle_\lambda$$

$$\partial_{x_i} \langle \Delta E(x_1, \dots, x_N) \rangle_\lambda = 0$$

$$\langle \partial_\lambda E \rangle_\lambda = \sum_{i=1}^N \int_{-\infty}^{\infty} \Delta E \partial_\lambda p(x_1, \dots, x_N | \lambda) \frac{\partial_\lambda p(x_i | \lambda)}{p(x_i | \lambda)} dx_1 \dots dx_N$$

using Cauchy-Schwarz's inequality

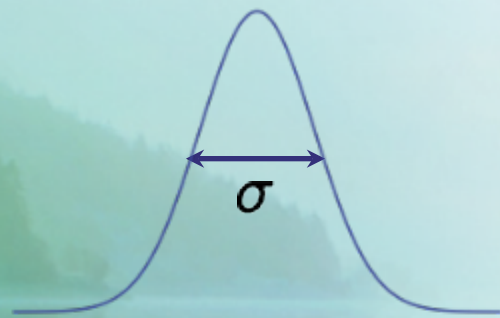
$$\sqrt{\frac{\langle (\Delta E)^2 \rangle}{|\langle \partial_\lambda \langle E \rangle_\lambda \rangle|^2}} \geq 1 / \sqrt{NF(\lambda)}$$

Cramer-Rao inequality

$$F(\lambda) = \int_{-\infty}^{\infty} \frac{1}{p(x|\lambda)} (\partial_x p(x|\lambda))^2 dx$$

Fisher information

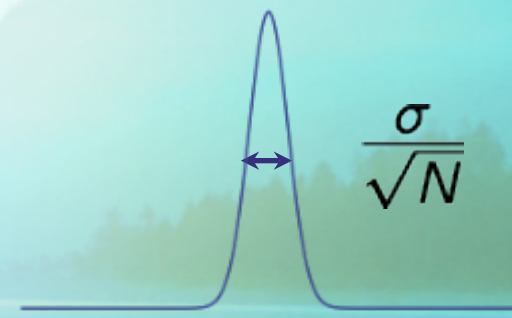
classical estimation



repetition of experiments



central limit theorem



estimator: mean value of the measurement outcomes

quantum estimation

probability of the outcome x :

$$p(x|\lambda) = \text{Tr}[\Pi_x \rho(\lambda)]$$

quantum Fisher information:
[independent of measurements]

$$F^{(Q)}(\lambda, N)$$

**quantum Cramer-Rao
inequality**

$$\delta\lambda \geq 1/\sqrt{F^{(Q)}(\lambda, N)}$$

symmetric logarithmic derivative (SLD)

$$(1/2)[L_\lambda \rho(\lambda) + \rho(\lambda) L_\lambda] = \partial_\lambda \rho(\lambda)$$

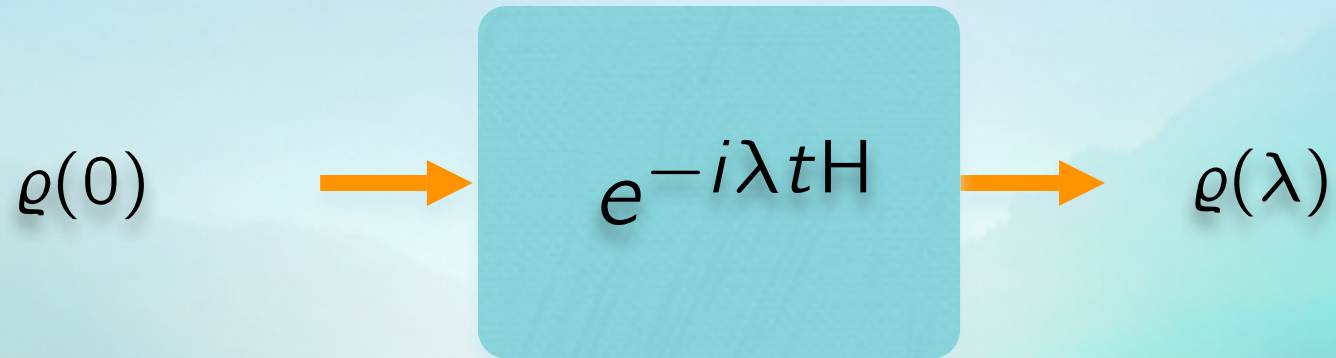
for pure states

$$L_\lambda = 2\partial_\lambda \rho(\lambda)$$

QFI

$$F^{(Q)} = \text{Tr}[\rho(\lambda) L_\lambda^2]$$

quantum estimation in **closed** systems



$$H(\lambda) = \lambda H$$

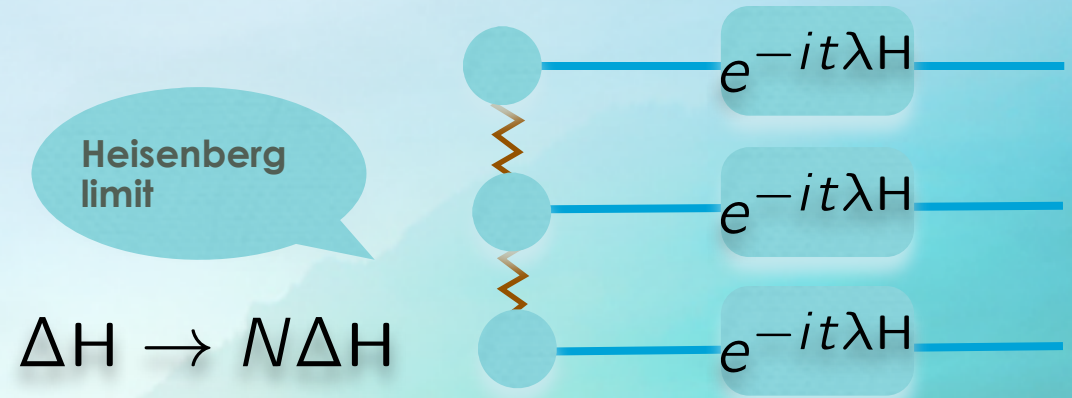
$$\partial_\lambda \rho(\lambda) = -it[H, \rho(\lambda)]$$

$$F^{(Q)} \leq 4t^2(\Delta H)^2 \equiv 4t^2 \text{Cov}_\rho(H, H)$$

$$\Delta\lambda \geq 1/(2t\Delta H)$$

quantum estimation in closed systems

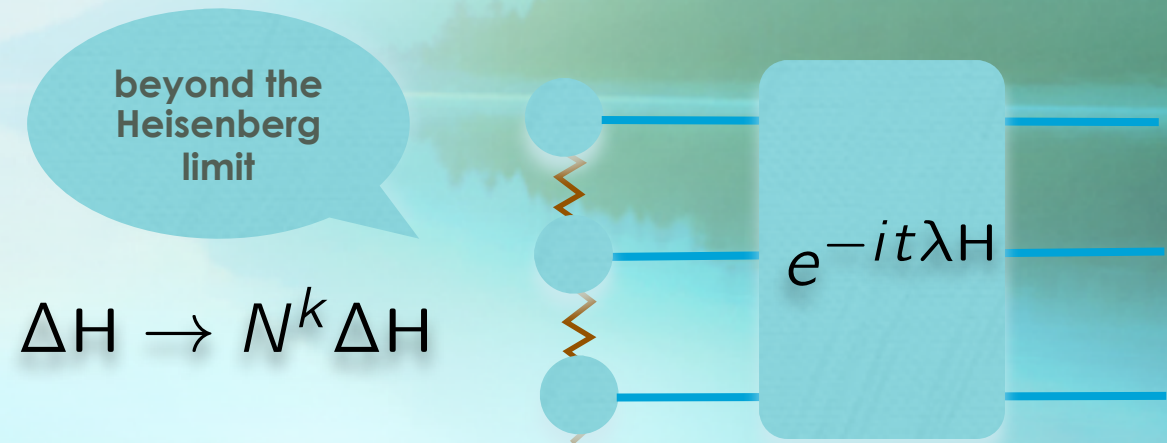
entanglement



[V. Giovannetti, S. Lloyd, and L. Maccone, PRL (2006)]

k -body interaction

$$H = \lambda \sum_{i_1, \dots, i_k} h_{i_1, \dots, i_k}$$



[Boixo et al., PRL (2007)]

calculation of QFI is difficult for **mixed states**

approaches:

- purification with an ancilla [Escher et al., Nature Physics (2011)]
- purification with vectorization [SA, M. Mehboudi, and A. T. Rezakhani, PRL (2014)]
[F. Benatti, SA, and A.T. Rezakhani, New J. Phys. (2014)]
- extending the definition of SLD to non-Hermitian domain
- calculating QFI in terms of the QFI of compatible decompositions
- ... [SA, arXiv:1403.8033]

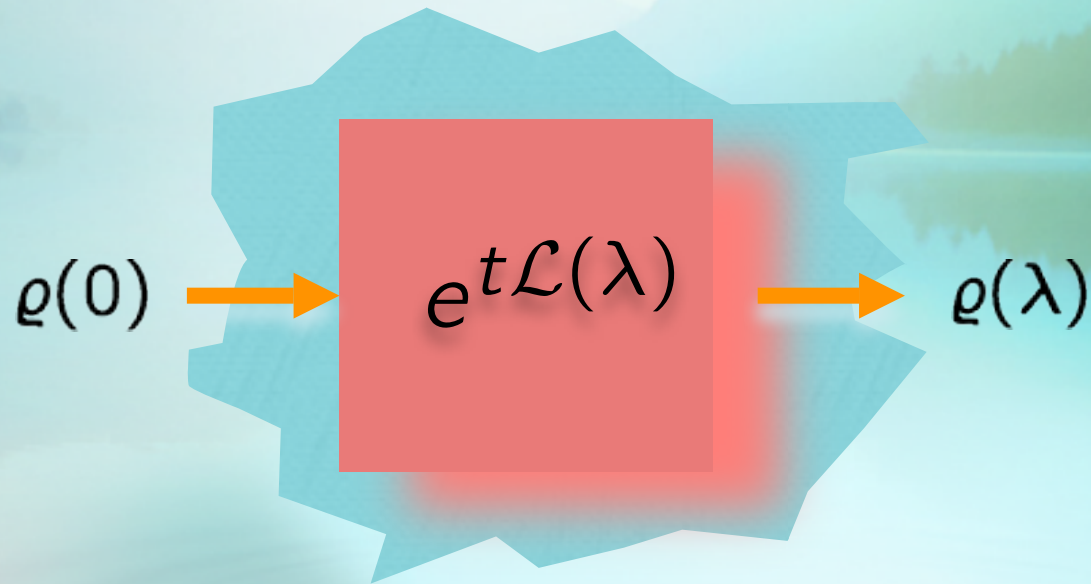
general dynamics:

$$\rho(t, \lambda) = \sum_i A_i(t, \lambda) \rho(0) A_i^\dagger(t, \lambda)$$

Kraus representation

dynamics with a generator:

$$\rho(t, \lambda) = e^{t\mathcal{L}(\lambda)}[\rho(0)]$$



purification with an ancilla

$$\mathcal{F}^{(Q)} = 4 \min_{\{A_i\}} \left(\langle H_1 \rangle_{\rho_0} - \langle H_1 \rangle_{\rho_0}^2 \right)$$

$$H_1 = \sum_i \partial_\lambda A_i^\dagger \partial_\lambda A_i$$

$$H_2 = i \sum_i A_i^\dagger \partial_\lambda A_i$$

- for any set of Kraus operators one may find an **UPPER** bound on QFI
- the bound is achievable, but it needs optimization

[Escher et al., Nature Physics (2011)]

dissipative Cramer-Rao bound (in terms of generator)

for simplification:

$$\mathcal{L}(\lambda) = \lambda L$$

vectorization:

$$|\varrho(t, \lambda)\rangle\rangle = e^{t\tilde{\mathcal{L}}(\lambda)}|\varrho(0)\rangle\rangle$$

normalized pure state

$$\tilde{\varrho}(t; \lambda) = |\varrho(t; \lambda)\rangle\rangle\langle\langle\varrho(t; \lambda)| / \text{Tr}[\varrho^2(t; \lambda)]$$

SLD:

$$\tilde{L}_\lambda = 2\partial_\lambda \tilde{\varrho}$$

generalized QFI:

$$\tilde{\mathcal{F}} = 4t^2 \text{Cov}_{\tilde{\varrho}}[\tilde{L}^\dagger, \tilde{L}]$$

$$\delta\lambda \propto 1/\Delta H$$

$$\text{error} \propto 1/\Delta \text{generator}$$

$$\text{Cov}_{\tilde{\varrho}}[\tilde{L}^\dagger, \tilde{L}] = \text{Tr}[\tilde{\varrho}\tilde{L}^\dagger\tilde{L}] - \text{Tr}[\tilde{\varrho}\tilde{L}^\dagger]\text{Tr}[\tilde{\varrho}\tilde{L}]$$

how dose the generalized QFI relate to the QFI of the system?

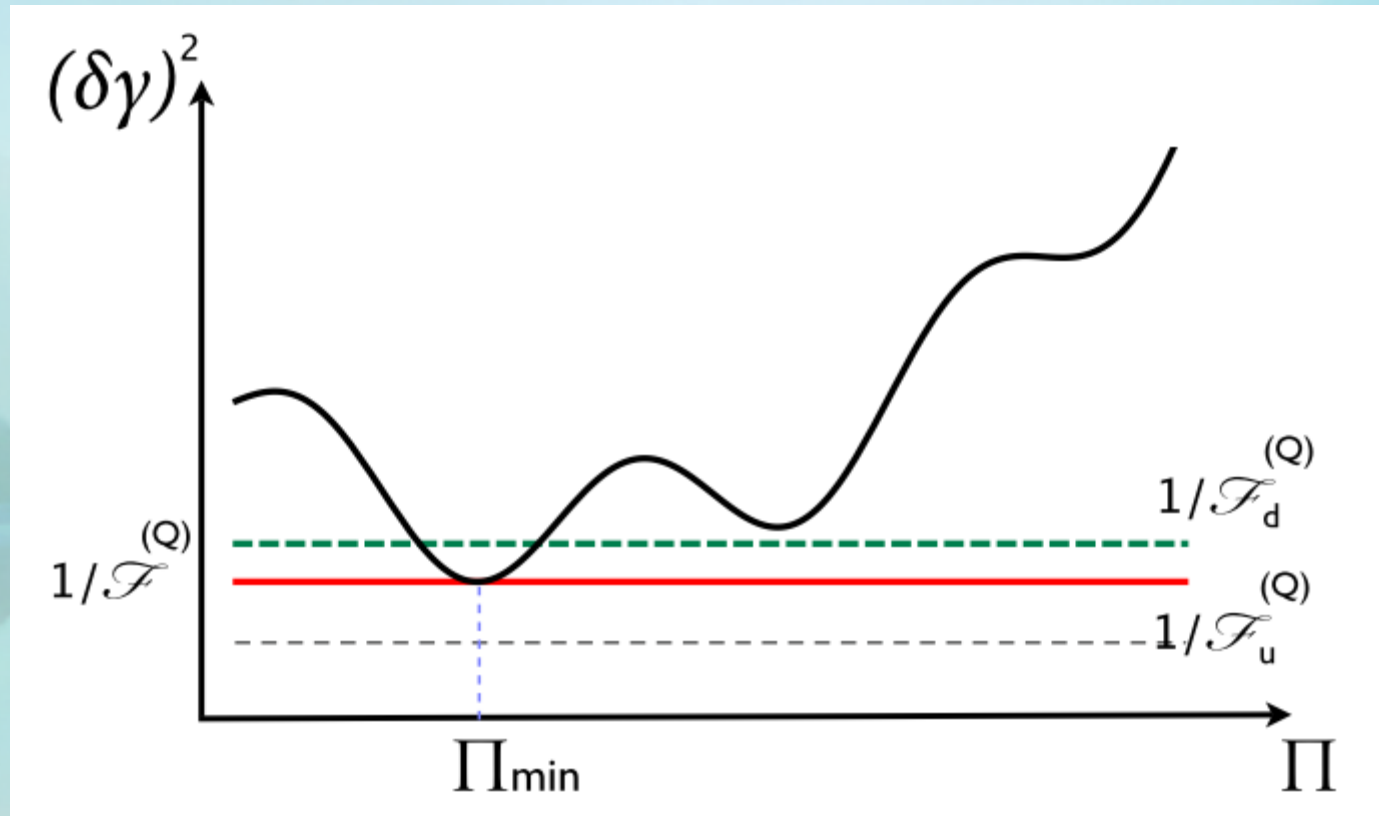
$$L_{\tilde{\rho}} = L_{\rho} \otimes I + I \otimes L_{\rho}^T - \partial_x \ln \text{Tr}[\rho^2]$$

$$\tilde{\mathcal{F}}(Q) = \frac{2}{\text{Tr}[\rho^2]} \left(\text{Tr}[\rho L_{\rho} \rho L_{\rho}] + \text{Tr}[\rho^2 L_{\rho}^2] - 2 \frac{(\text{Tr}[\rho^2 L_{\rho}])^2}{\text{Tr}[\rho^2]} \right)$$

a LOWER bound on the QFI

$$\frac{\text{Tr}[\rho^2]}{4\lambda_{\max}(\rho)} \tilde{\mathcal{F}}(Q) \leq \mathcal{F}(Q) \leq \frac{\text{Tr}[\rho^2]}{4\lambda_{\min}(\rho)} \tilde{\mathcal{F}}(Q) + F(\rho)$$

LOWER bound vs. UPPER bound



non-Hermitian SLD (dynamical bound)

motivation:

time derivative of ϱ $\partial_\tau \varrho = -i[x_0 H, \varrho] + \sum_i x_i \Gamma_i \varrho \Gamma_i^\dagger - \frac{1}{2} \{ \Gamma_i^\dagger \Gamma_i, \varrho \}$

\equiv **non-Hermitian**

$\partial_\tau \varrho = D_\varrho \varrho + \varrho D_\varrho^\dagger$

where

$$D_\varrho := -ix_0 H - \frac{1}{2} \sum_i x_i (\Gamma_i^\dagger \Gamma_i - \Gamma_i \varrho \Gamma_i^\dagger \varrho^{-1})$$

generalization:

nSLD $\partial_x \varrho = (L_\varrho \varrho + \varrho L_\varrho^\dagger)/2 \longrightarrow \mathcal{F}^{(Q)}(x) \leq \text{Tr}[L_\varrho \varrho L_\varrho^\dagger] =: \mathcal{F}_{\text{ul}}^{(Q)}(x)$

NB. non-Hermitian right logarithmic derivative operators have already been used in the literature [Fujiwara and Imai, JPA (2008)]

a general Lindblad equation

$$\partial_\tau \rho = -i[x_0 H, \rho] + \sum_i x_i (\Gamma_i \rho \Gamma_i^\dagger - \frac{1}{2} \{\Gamma_i^\dagger \Gamma_i, \rho\})$$

estimation of x_0

$$\partial_{x_0} \rho = -i\tau [H - \langle H \rangle_\rho, \rho] \longrightarrow L_0 = -2i\tau (H - \langle H \rangle_\rho)$$

$$\mathcal{F}_{u1, x_0}^{(Q)} = 4\tau^2 \Delta_\rho^2 H$$

estimation of x_i

$$\partial_{x_i} \rho = \tau (\Gamma_i \rho \Gamma_i^\dagger - \frac{1}{2} \{\Gamma_i^\dagger \Gamma_i, \rho\}) \longrightarrow L_i = \tau (\Gamma_i \rho \Gamma_i^\dagger \rho^{-1} - \Gamma_i^\dagger \Gamma_i)$$

$$\mathcal{F}_{u1, x_i}^{(Q)} = \tau^2 \left(\langle (\Gamma_i^\dagger \Gamma_i)^2 \rangle_\rho - 2 \langle \Gamma_i^{\dagger 2} \Gamma_i^2 \rangle_\rho + \text{Tr}[\rho^{-1} (\Gamma_i \rho \Gamma_i^\dagger)^2] \right)$$

dephasing quantum channel:

$$\partial_\tau \rho = -ix_0 [H, \rho] + x_1 (\sigma_z \rho \sigma_z - \rho)$$

entangled initial state: $(|0\rangle^{\otimes N} + |1\rangle^{\otimes N})/\sqrt{2}$

$$\mathcal{F}_{u1}^{(Q)} = N^2 \tau^2 / (e^{2N\tau x} - 1)$$

$$\mathcal{F}^{(Q)} = N^2 \tau^2 / e^{2N\tau x}$$

kinematic bound

convex decomposition: $\rho = \sum_i p_i \rho_i$

$$\partial_x(p_i \rho_i) = (1/2)[L_i p_i \rho_i + p_i \rho_i L_i]$$

kinematic bound on the QFI:

$$\mathcal{F}_{u2}^{(Q)} = \mathcal{F}^{(c)}(\{p_i\}) + \sum_i p_i \mathcal{F}_i^{(Q)}$$

[Demkowicz-Dobrzanski et al., Nature Communications (2012)] [Fujiwara, PRA (2001)]

classical FI of probability distribution:

$$\mathcal{F}^{(c)}(\{p_i\}) = \sum_i (\partial_x p_i)^2 / p_i$$

transition from classical to quantum:

$$\mathcal{F}_{u2}^{(Q)} = c_1(\alpha, q, \tau)N + c_2(\alpha, q, \tau)N^2$$

transition point: $N^* = \frac{c_1}{c_2}$

example:

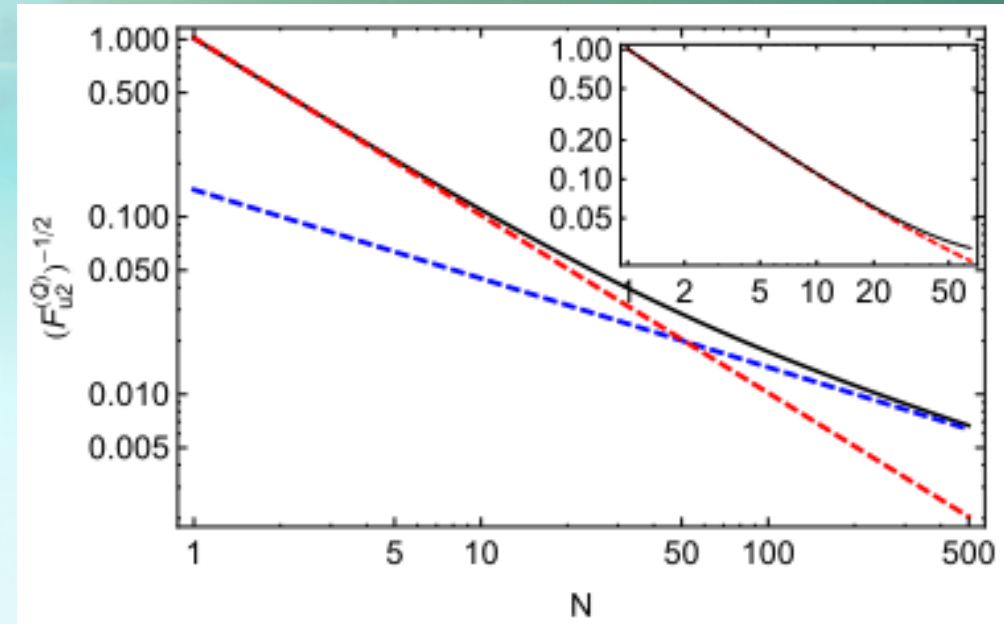
$$A_1 = (\sqrt{q} \cos[\alpha\omega] + i\sqrt{1-q} \sin[\alpha\omega] \sigma_z) e^{i\omega\tau\sigma_z/2}$$

$$A_2 = (i\sqrt{q} \sin[\alpha\omega] + \sqrt{1-q} \cos[\alpha\omega] \sigma_z) e^{i\omega\tau\sigma_z/2}$$

$$\rho(0) = |\text{GHZ}_N\rangle\langle\text{GHZ}_N|$$

QFI of each state:

$$\mathcal{F}_i^{(Q)} = \text{Tr}[\rho_i L_i^2]$$



kinematic upper bound + nSLD : purification with ancilla

Kraus representation

$$\varrho_\tau(\mathbf{x}) = \sum_i A_i(\mathbf{x}, \tau) \varrho_0 A_i^\dagger(\mathbf{x}, \tau)$$

a natural decomposition: \longrightarrow $p_i = \text{Tr}[A_i \varrho_0 A_i^\dagger]$ $\varrho_i = A_i \varrho_0 A_i^\dagger / \text{Tr}[A_i \varrho_0 A_i^\dagger]$

using nSLD:

$$\partial_{\mathbf{x}}(p_i \varrho_i) = (\mathbf{L}_i p_i \varrho_i + p_i \varrho_i \mathbf{L}_i^\dagger) / 2$$

$$\mathbf{L}_i A_i = 2\partial_{\mathbf{x}} A_i + i\alpha A_i$$

applying on the kinematic bound

$$\mathcal{F}_{u2}^{(Q)} = \sum_i 4(\langle \partial_{\mathbf{x}} A_i^\dagger \partial_{\mathbf{x}} A_i \rangle_{\varrho_0} - i\alpha \langle A_i^\dagger \partial_{\mathbf{x}} A_i \rangle_{\varrho_0}) + \alpha^2$$

optimization:

$$\mathcal{F}_{u2}^{(Q)}(\mathbf{x}) = 4\left(\langle \mathbf{H}_1 \rangle_{\varrho_0} - \langle \mathbf{H}_2 \rangle_{\varrho_0}^2\right)$$

where:

$$\mathbf{H}_1 = \sum_i \partial_{\mathbf{x}} A_i^\dagger \partial_{\mathbf{x}} A_i$$

$$\mathbf{H}_2 = i \sum_i A_i^\dagger \partial_{\mathbf{x}} A_i$$



Thanks