

Algorithmic Quantum Simulation

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What is Q Simulation?

*Employing a computational machine to mimic certain physical Q systems thereby answering relevant C-intractable questions **accurately** and **efficiently**.*

- **Accuracy**: bounded error ϵ .
- **Efficiency**: cost (e.g., time and space) of simulation scales 'reasonably' (polynomially) with the problem size.

An aim of Q sim: simulating Schrödinger's Equation

- Schrödinger's equation:

$$i \frac{d}{dt} |\psi(t)\rangle = \hat{H}(t) |\psi(t)\rangle.$$

- Unitary dynamics ($\hbar \equiv 1$):

$$\hat{H} = \hat{H}^\dagger \implies |\psi(t)\rangle = \mathcal{T} \exp \left\{ -i \int_0^t du \hat{H}(u) \right\} |\psi(0)\rangle.$$

- Time-independent: $|\psi(t)\rangle = \exp \left\{ -i \hat{H} t \right\} |\psi(0)\rangle$
- Different solutions with different complexity:
 - solve $|\psi(t)\rangle$ over some time domain;
 - determine the spectrum of \hat{H} ;
 - find eigenvectors of \hat{H} , e.g. the ground state;
 - estimate the mean of an observable $\langle \psi(t) | \hat{O} | \psi(t) \rangle$.
- Some quantities could be tractable whereas others not so.

Some C methods for simulating Schrödinger's Equation

- Diagonalize \hat{H} ; then algebraic.
- Integrate:
 - Runge-Kutta;
 - Magnus expansions = Baker-Campbell-Hausdorff method;
 - Product formulæ:
 - Forest-Ruth = symplectic integration;
 - Trotter-Suzuki;
 -
- Quantum Monte Carlo simulations:
 - Stochastic Green functions;
 - Variational, diffusion or path-integral Monte-Carlo methods.
- Density matrix renormalization group.

Wiebe Berry Høyer BCS *J. Phys. A* **43** 065203 (2010).

Feynman: Simulating Physics with Computers

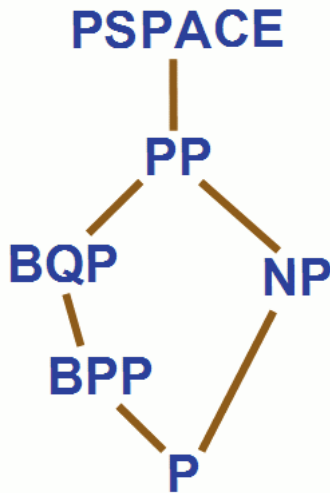
§5. Can Q systems be probabilistically simulated by a C computer?

Can a Q system be probabilistically simulated by a C (probabilistic, I'd assume) universal computer? In other words, a computer which will give the same probabilities as the Q system does. If you take the computer to be the C kind I've described so far, (not the Q kind described in the last section) and there're no changes in any laws, and there's no hocus-pocus, the answer is certainly, No! This is called the hidden-variable problem: it is impossible to represent the results of Q mechanics with a C universal device.

Feynman *Int. J. Th. Phys.* **21** (1982) pp. 467–488.

Decision problems & complexity (Aaronson's schematic)

- How hard to solve Yes/No problem.
- Employ algorithm (input, output, procedure using instruction set).
- Instance size: n bits for input.
- Complexity: resource scaling (T & S) vs n .
- $\text{PSPACE} \subset \text{EXP}$.
- PP: $Y \implies$ output Y w/pr $\geq 1/2$;
 $N \implies$ output Y w/pr $\leq 1/2$.
- BPP: $Y \implies$ output Y w/pr $\geq 2/3$;
 $N \implies$ output Y w/pr $\leq 1/3$.



Feynman exegesis

- Heisenberg picture (matrices) \implies q problems \subset EXP.
- Feynman path integral \implies q problems \subset PP.¹
- “give the same probabilities” \implies q algorithm efficiently answers decision problems concerning expectation values $\langle \psi | \hat{O} | \psi \rangle$ with bounded error.
- “classical kind ... the answer is certainly, No!” \implies some of these problems $\not\subset$ BPP.²
 - P=BPP generally believed.
 - Implication $\text{BPP} \subset \text{BQP}$ would be significant if proved.
 - Feynman says “No!” because of “the hidden-variable problem: it is impossible to represent the results of quantum mechanics with a classical universal device”. Correct?
- Aside: post-selected quantum computing is $\text{PostBQP} = \text{PP}$.

Approximate simulation of (known) \hat{H} -generated evolution

Simulating within tolerance ϵ .

- Treat case of time-independent $\hat{H}^{(n)}$;
- Resultant evolution over time t : $U = \exp \left\{ -i\hat{H}^{(n)}t \right\}$;
- Evolution: $|\psi(t)\rangle = \exp \left\{ -i\hat{H}t \right\} |\psi(0)\rangle$;
- Simulated state $|\tilde{\psi}(t)\rangle$ has error: $\| |\tilde{\psi}(t)\rangle - |\psi(t)\rangle \|$;
- Input: $\epsilon =$ upper bound to allowed worst-case error.

Raeisi Wiebe BCS *New J. Phys.* **14** 103017 (2012).

Decomposing an n -qubit k -local $\hat{H}^{(n)}$

Write the Hamiltonian as a sum of simpler Hamiltonians

- Express evolution as sequence of evolutions generated by simpler Hamiltonians;
- Let $\hat{h}_j^{(n)} = \otimes_{\ell=1}^n \hat{\Xi}_{j\ell}^{(n)}$ act on $k \in \text{polylog}(n)$ qubits;
- Each $\hat{\Xi}_{j\ell}^{(n)}$ drawn from

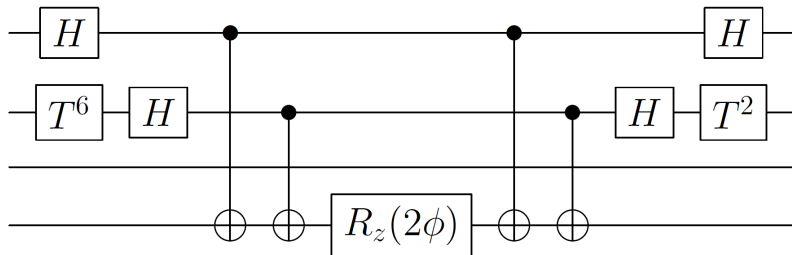
$$\left\{ \mathbb{1}, X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, Y = i \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}, Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\}$$
 & is non- $\mathbb{1}$ for $\leq k$ instances in tensor product;
- k -local $\hat{H}^{(n)}$: $\sum_{j=1}^{m \in \text{poly}(n)} \hat{h}_j^{(n)}$.

Raeisi Wiebe BCS *New J. Phys.* **14** 103017 (1982).

Quantum circuit component for Pauli evolution

Unitary evolution generated by \hbar_j

$$U_j = \exp \left\{ -i\hbar_j^{(n)} t \right\}$$



$$\exp \left\{ -i\phi X \otimes Y \otimes \mathbb{1} \otimes Z \right\}$$

Sequence of \hat{H} -generated evolutions

Generating and multiplying evolution operators.

- Partition time interval $\Delta t = t/r$, namely (t_1, \dots, t_M) ;
- $U(\Delta t) \approx \exp \left\{ -i a_{j_M} \mathfrak{h}_{j_M}^{(n)} t_M \right\} \cdots \exp \left\{ -i a_{j_1} \mathfrak{h}_{j_1}^{(n)} t_1 \right\}$.

General case: time-ordered exponential

$$\mathcal{T} \exp \left\{ -i \int_t^{t+\Delta t} du \sum_{j=1}^m \hat{H}_j(u) \right\} \approx \prod_{q=1}^M \exp \left(-i \hat{H}_{j_q}(t_q) \Delta t_q \right).$$

Trotter product formula

$$e^{it(\hat{h}+\hat{h}')} \rightarrow \lim_{n \rightarrow \infty} \left(e^{it\hat{h}/n} e^{it\hat{h}'/n} \right)^n. \text{ Error } \epsilon \text{ is important.}$$

Raeisi Wiebe BCS *New J. Phys.* **14** 103017 (1982).

Minimizing time cost using Suzuki's iterative algorithm

Suzuki's generalization of the Trotter formula

$$S_2(\lambda) = \prod_{j=1}^m e^{\hat{H}_j \lambda / 2} \prod_{j'=m}^1 e^{\hat{H}_{j'} \lambda / 2},$$

$$S_{2k}(\lambda) = [S_{2k-2}(p_k \lambda)]^2 S_{2k-2}((1 - 4p_k) \lambda) [S_{2k-2}(p_k \lambda)]^2,$$

for $p_k = (4 - 4^{1/(2k-1)})^{-1}$. Each iteration k has $5\times$ as many terms as for iteration $k - 1$.

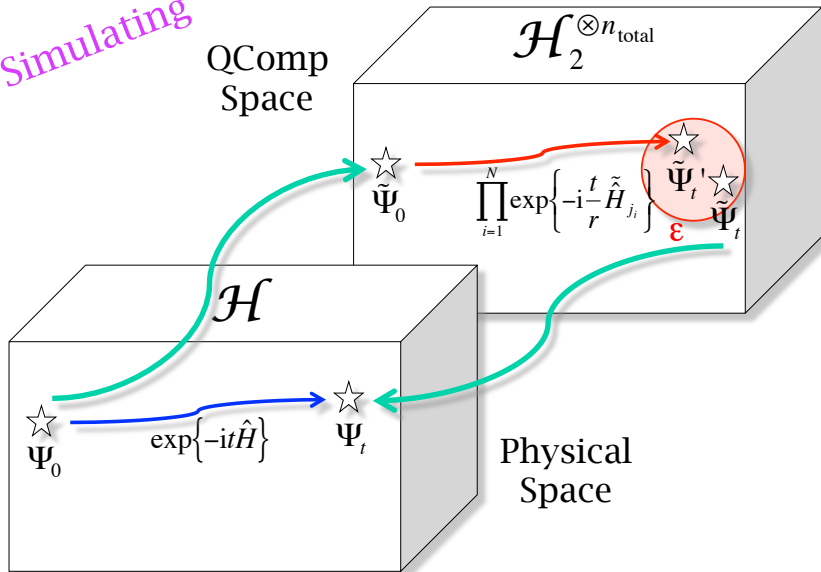
Suzuki proves for small λ :

$$\left\| \exp \left\{ \sum_{j=1}^m \hat{H}_j \lambda \right\} - S_{2k-1}(\lambda) \right\| \in O(|\lambda|^{2k+1}).$$

Suzuki *Phys. Lett. A* **146** 319 (1990),

Suzuki *J. Math. Phys.* **32** 400 (1991).

Simulating



Hamiltonian in a black-box

- Previously designed algorithm exploits knowledge of $\hat{H}^{(n)}$;
- Black-box setting: algorithm without knowledge of $\hat{H}^{(n)}$;
- $\hat{H}^{(n)}$ is queried during algorithm;
- $\hat{H}^{(n)}$ is exponentially large in n ;
- Require simplifying promises for $\hat{H}^{(n)}$ to reduce cost;
- **Objective** is to construct an efficient algorithm for any Hamiltonian subject to reasonable promises.

Lloyd's 1996 formalization of efficient Q computing

Assumed tensor-product structure and used

$$\exp \left\{ -it \sum_{j=1}^m \hat{H}_j \right\} = \left(\prod_{i=1}^N \exp \left\{ -i \frac{t}{r} \hat{H}_{j_i} \right\} \right)^r + \sum_{j > j'} [\hat{H}_j, \hat{H}_{j'}] \frac{t^2}{2r} + \epsilon$$

to prove polyn time T and space S costs.

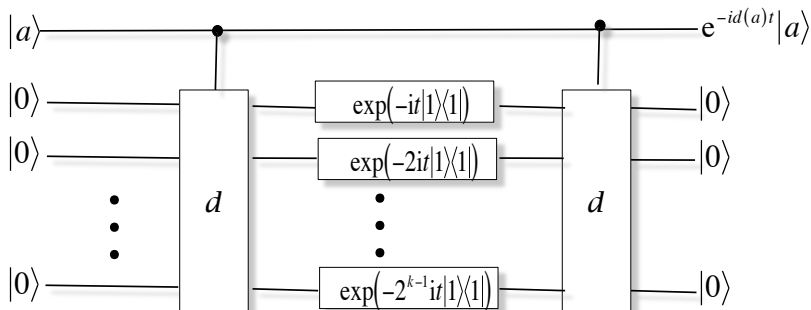
Simulating evolution for one-sparse $\hat{H}^{(n)}$

Simulating evolution for diagonal \hat{H} with $d(a) = \langle a|\hat{H}|a\rangle \in \{0, 1\}^k$.

$|a, 0\rangle \mapsto |a, d(a)\rangle \mapsto \exp\{-itd(a)\}|a, d(a)\rangle \mapsto \exp\{-itd(a)\}|a, 0\rangle$.

Circuit for one-sparse Hamiltonian evolution is a minor modification of diagonal- $\hat{H}^{(n)}$ circuit.

Childs Cleve Deotto Farhi Gutmann Spielman *STOC'03* **146** 59–68.

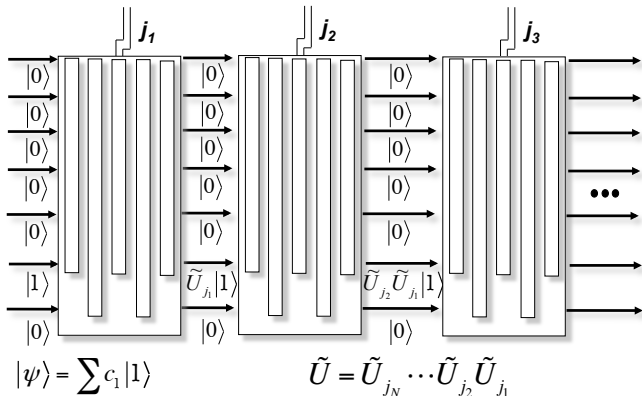


Simulating evolution for one-sparse \hat{H}

General evolution as sequence of one-sparse Hamiltonian evolutions

Approximately & efficiently decompose the overall evolution

$U \approx \prod_{\nu=1}^N U_{j_\nu}$ each generated by one-sparse \hat{H}_{j_i} .



Q state generation [Aharonov & Ta-Shma (AT) 2003]

- Motivated by claims of adiabatic Q computing solving NP-Hard problems (still relevant today³).
- Consider which Q states can be efficiently generated.
- Oracle setting: efficiently queries elements of \hat{H} .
- No assumption of tensor-product structure (c.f. Lloyd).
- Demonstrate equivalence between QSG and statistical zero knowledge (SZK) problems.
 - ZK proof: prove knowledge of secret without revealing secret.
 - SZK problems: discrete log, quadratic residuosity,
 - Specifically show SZK problems reducible to QSG problems.

Considerations for efficient quantum simulation

- Problem size: Number n of qubits in the system.
- Accuracy: The answer is no worse than ϵ (appropriate metric).
- Efficient: Solve with resource consumption $\in O(\text{poly}\frac{n}{\epsilon})$.
- Generality: Solves problems for a broad class of systems.

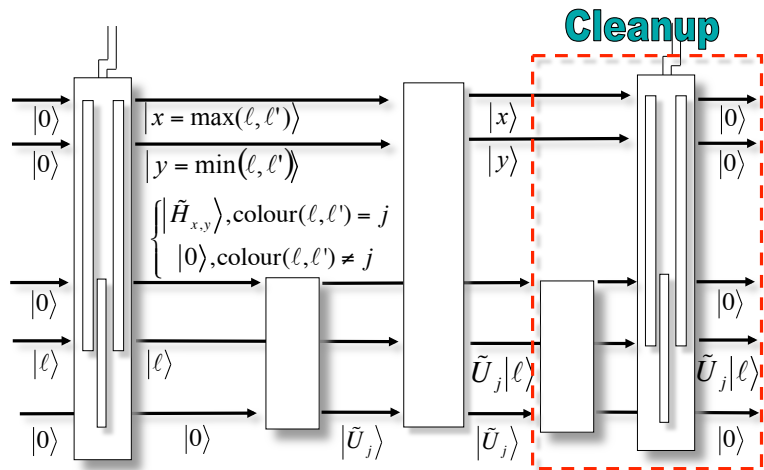
Sparse Hamiltonian Lemma (Aharonov & Ta-Shma STOC 2003)

If \hat{H} acting on n qubits is d -sparse s.t. $d \in O(\text{polyn})$ & the list of nonzero entries in each row is efficiently computable, then \hat{H} is *simulatable* if $\|\hat{H}\| \leq \text{polyn}$.

Childs's rules for simulatability

- $\sum_i \hat{H}_i$ with each \hat{H}_i acting on $O(1)$ qubits or
- is a $\sqrt{-1}$ commutator of two simulatable \hat{H}_i s or
- convertible to simulatable \hat{H} by efficient unitary conjugation or
- is sparse and efficiently computable

Aharonov & Ta-Shma Circuit (Wiebe's picture)



Simulation cost is slightly superlinear in time $t^{1+o(1)}$

Theorem [Berry, Ahokas, Cleve, Sanders 2007 (BACS)]

$$M \leq \frac{m5^{2k}(mq_k\tau)^{1+1/2k}}{2[(2k+1)!\epsilon]^{1/2k}}$$

Optimize

$$k \approx \frac{1}{2} \sqrt{\log_5 \left(\frac{m\tau}{\epsilon} \right)}.$$

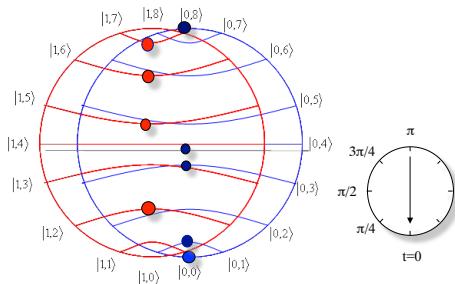
$$M \leq 2m^2\tau \exp \left\{ 2 \sqrt{\log_5 \left(\frac{m\tau}{\epsilon} \right)} \right\} \approx \frac{1}{2} \sqrt{\log_{5/\sqrt{3}} \left(\frac{m\tau}{\epsilon} \right)} \quad (1)$$

Black-box Q simulation must be superlinear in time

Theorem (No Quantum Speedup)

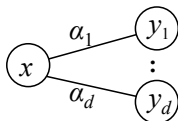
For all positive integers $N \exists$ a row-computable two-sparse \hat{H} s.t. simulating \hat{H} -generated evolution for (scaled) time $\tau = \pi N/2$ within precision $1/4$ requires $\geq \tau/2\pi$ queries to \hat{H} .

$$X_j = \underline{0} \quad \underline{1} \quad \underline{1} \quad \underline{0} \quad \underline{1} \quad \underline{0} \quad \underline{0} \quad \underline{1}$$

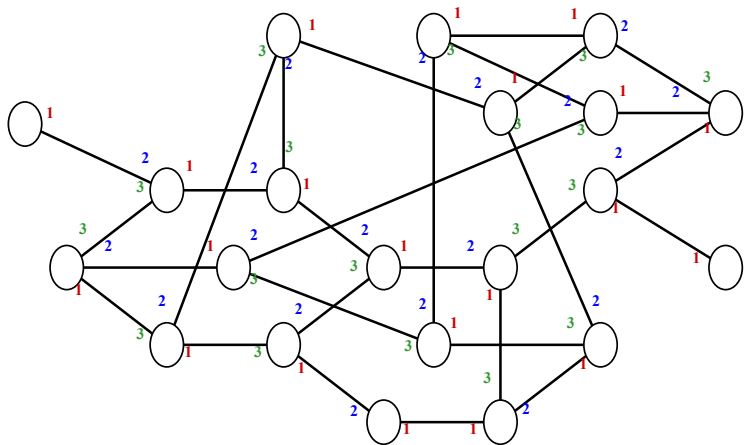


Hamiltonians as weighted graphs (Cleve's picture)

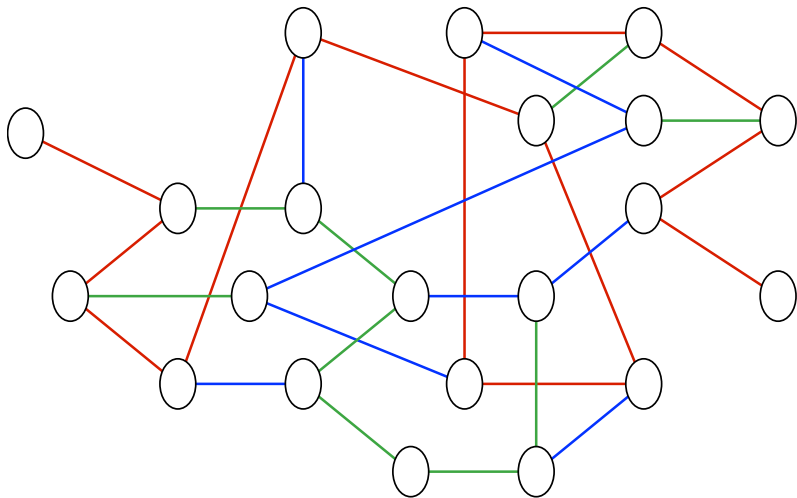
- For column x , only rows y_1, \dots, y_d hold nonzero matrix elements.
- The graph weight α_i is $\langle x | \hat{H} | y_i \rangle$.
- As $\hat{H} = \hat{H}^\dagger$, α_i^* is the weight for column y_i and row x .
- Hermitian \hat{H} can be represented by a degree d graph.
- Goal: decompose \hat{H} graph into disjoint union of $d = 1$ graphs.



Colouring the graph for \hat{H} with d^2 labels (Cleve's picture)

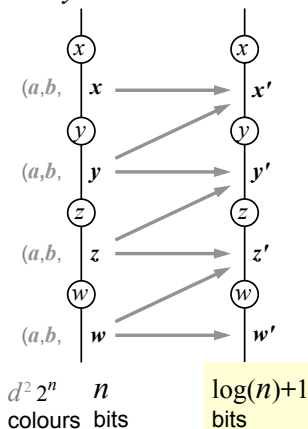


Problem: long monochromatic paths (Cleve's picture)



Colouring by Cole-Vishkin coin tossing [Cleve picture]

$$x < y < z < w$$



“Deterministic coin-tossing” [Cole & Vishkin '86]

$$y' \leftarrow (i, y_i), \text{ where } i = \min \{j : y_j \neq z_j\}$$

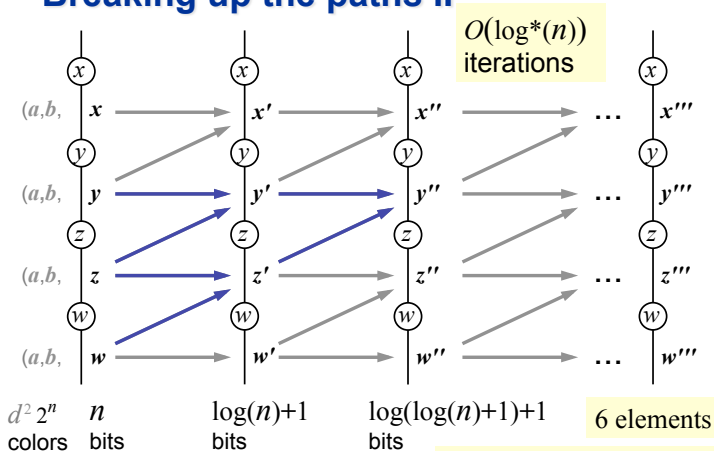
Example: $y = 01100101$
 $z = 01001101$

Then $y' = (010, 1)$

Note: still a valid coloring!
 $x' \neq y'$ & $y' \neq z'$ & $z' \neq w'$

Colouring by Cole-Vishkin coin tossing [Cleve picture]

Breaking up the paths II



Just 5 iterations for $n \leq 10^{10^{37}}$

Time and space costs for simulating \hat{H} -generated evolution

Who	Year	T	S
Lloyd	1996	$O(t^2)$	$O(n)$
AT ⁴	2003	$O\left(n^9 d^4 \frac{t^2}{\epsilon}\right)$	$O(n)$
Childs ⁵	2003	$O\left(n^2 d^{4+o(1)} \frac{t^{3/2}}{\sqrt{\epsilon}}\right)$	$O(n)$
BACS ⁶	2007	$O\left(\log^* n d^{4+o(1)} \frac{t^{1+1/2k}}{\epsilon^{1/2k}}\right)$	$O(n \log^* n)$
CK ⁷	2010	$O\left(\left[d^3 + d^2 \log^* n\right] \frac{t^{1+1/2k}}{\epsilon^{1/2k}}\right)$	$O(nd + n \log^* n)$
BC ⁸	2010	$O\left(\ \hat{H}\ _{\max} d \frac{t}{\sqrt{\epsilon}}\right)$	•

Simulating many-body systems

Abrams & Lloyd PRL 1996

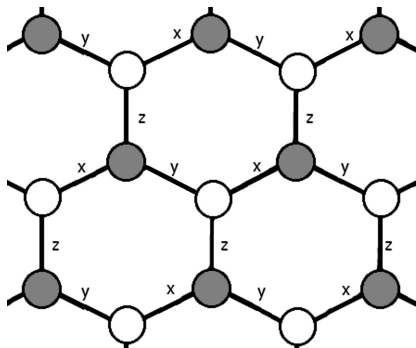
But the problem of simulation — that is, the problem of modeling the full time evolution of an arbitrary Q system — is less technologically demanding. While thousands of qubits and billions of Q logic operations are needed to solve C difficult factoring problems [16], it would be possible to use a Q computer with only a few tens of qubits and a few thousand operations to perform simulations that would be C intractable [17].

$$\hat{H}_{\text{Hubbard}} = -t \sum_{\langle i,j \rangle, \sigma} \left(\hat{c}_{i\sigma}^\dagger \hat{c}_{j\sigma} + \hat{c}_{j\sigma}^\dagger \hat{c}_{i\sigma} \right) + U \sum_{i=1}^N \hat{n}_{i\uparrow} \hat{n}_{i\downarrow},$$

$$\hat{H}_{\text{Bose-Hubbard}} = -t \sum_{\langle i,j \rangle} \left(\hat{c}_{i\sigma}^\dagger \hat{c}_j + \hat{c}_j^\dagger \hat{c}_i \right) + \frac{U}{2} \sum_{i=1}^N \hat{n}_i (\hat{n}_i - \mathbf{1}) - \mu \sum_{i=1}^N \hat{n}_i.$$

Examples: models for simulation

- $\hat{H}_{\text{Ising}} = J \sum_{\langle i,j \rangle} Z_i \otimes Z_j + B \sum_i X_i.$
- $\hat{H}_{XY} = J_x \sum_{\langle i,j \rangle} X_i \otimes X_j + J_y \sum_{\langle i,j \rangle} Y_i \otimes Y_j.$
- $\hat{H}_{\text{Heisenberg}} = J_x \sum_{\langle i,j \rangle} X_i \otimes X_j + J_y \sum_{\langle i,j \rangle} Y_i \otimes Y_j$
- $\hat{H}_{\text{honeycomb}} =$
 $-J_x \sum_{x\text{-link}} X_i \otimes X_j - J_y \sum_{y\text{-link}} Y_i \otimes Y_j - J_z \sum_{z\text{-link}} Z_i \otimes Z_j$



Time-dependent Hamiltonian evolution

Problem:

For $\hat{H} = \sum_{j=1}^m \hat{H}_j$ with each Hamiltonian $\hat{H}_j : \mathbb{R} \rightarrow \mathbb{C}^{N \times N}$ P -differentiable, construct

$$U(t, t + \Delta T) := \mathcal{T} \exp \left\{ -i \int_t^{t+\Delta t} du \hat{H}(u) \right\}$$

as a product of N exponentials $\exp \left\{ -i \hat{H}_{j_P}(t_P) \Delta t_P \right\}$ within tolerance ϵ of $U(t, t + \Delta t)$, and find an upper bound for N .

Conditions for $\hat{H}(t)$ to be efficiently Q-simulatable

Theorem: Wiebe, Berry, Høyer, Sanders 2010

Let $\hat{H}(t) = \sum_{j=1}^m \hat{H}_j(t)$ with each $\hat{H}_j(t)$ $2k$ -differentiable on $[\mu, \mu + \Delta\lambda]$. Furthermore let timescale Λ satisfy

$$\Lambda = \sup_{\lambda \in [\mu, \mu + \Delta\lambda]} \max_{q=0, \dots, 2k, j=1, \dots, m} \left\| \partial_{\lambda}^q \hat{H}_j(t) \right\|^{1/(q+1)}$$

with

$$\epsilon \leq \frac{9}{10} \left(\frac{5}{3} \right)^k \Lambda \Delta\lambda$$

and $\max_{x > y} \|U(x, y)\| \leq 1$, then a decomposition $\tilde{U}(\mu + \Delta\lambda, \mu)$ can be constructed s.t. $\|\tilde{U} - U\| \leq \epsilon$ and s.t. the number of operator exponentials in \tilde{U} satisfies

$$M \leq \left\lceil 3m\Lambda\Delta\lambda k \left(\frac{25}{3} \right)^k \left(\frac{\Lambda\Delta\lambda}{\epsilon} \right)^{1/2k} \right\rceil$$

Q linear equation solver [Harrow Hassidim, Lloyd 2009]

Typical problem statement

Given matrix A and vector b , find x such that $Ax = b$; or given matrix A , vector b , and matrix M , find a good approximation of $x^T M x$ such that x such that $Ax = b$.

- Replace b by $|b\rangle = \sum_{i=1}^N b_i |i\rangle$ in computational basis.
- Then $|x\rangle = \hat{h}^{-1}|b\rangle$, but inverting \hat{h} is hard.
- \hat{h} has eigenvalues λ_j and eigenvectors $|u_j\rangle$ for $j = 1, \dots, N$.
- Express $|b\rangle = \sum_{j=1}^N \beta_j |u_j\rangle$.
- Idea: $|x\rangle = \hat{h}^{-1}|b\rangle \approx \sum_{j=1}^N \frac{\beta_j}{\lambda_j} |u_j\rangle$.
 - Kitaev phase-estimation approach: $\sum_{j=1}^N \beta_j |u_j\rangle |\lambda_j\rangle$.
 - Construct (non-unitary) linear map $|\lambda_j\rangle \mapsto \lambda_j^{-1} |\lambda_j\rangle$.
 - Uncompute $|\lambda_j\rangle$ to obtain approximate $|x\rangle$.

Summary

- Devised and costed efficient, accurate algorithms for Q simulation for \hat{H} held by an oracle.
- For oracle setting, an efficient query technique is developed to construct the Q simulation as a concatenation of Q circuits for one-sparse \hat{H} simulation.
- Run-time for Q algorithm is reduced by exploiting higher-order Suzuki method.
- Applications to many-body Q simulation.
- Q algorithms have been developed for time-dependent \hat{H} , which is relevant to adiabatic Q computing, controlled systems and Q phase transitions.
- Q could be used as a linear equation solver.